Essential Physics I

英語で物理学の エッセンス I

Lecture 8: 06-06-16

News



No lecture next week!



BUT!

There IS a lecture



6/20/2016 AND 6/23/2016 6月20日 6月20日 0.18:00 News

<section-header>

AND

There IS a lecture



2016 JULY						
SUN	MON	TUE	WED	THU	FRI	SAT
					1	2
3	\checkmark	5	6	7	8	9
10	11	12	13	14	15	16
17	18	19	20	21	22	23
24	25	26	27	28	29	30
31						



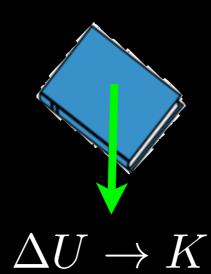
Potential energy:

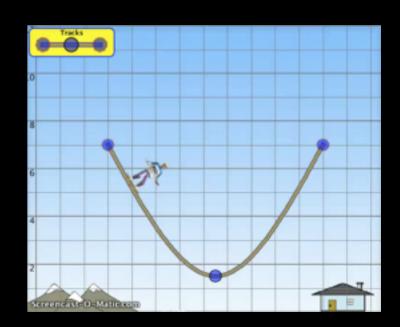
Gravity: Spring:

 $U = \frac{1}{2}kx^2$

 $\Delta U = -mg\Delta y$

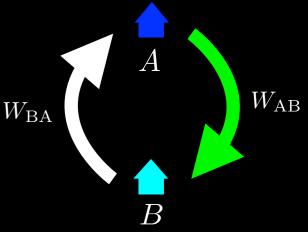
= stored energy we can get back as kinetic energy





If a force stores energy to give back later, it is **conservative**: total work around a closed path (start = end) is 0

$$\oint \bar{F} \cdot d\bar{r} = 0$$



A block of mass m starts from rest ($v_i = 0$) on a ramp at height, h.

It slides down the ramp and reaches a speed, v.

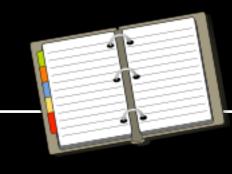
What height is needed to reached the speed 2v?

(a) h (b) 1.41h

(c) 2h

(d) 3h (e) 4h

(f) 6h

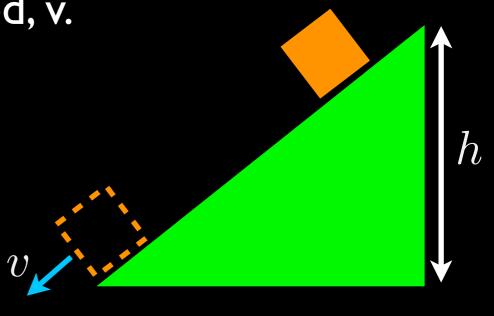


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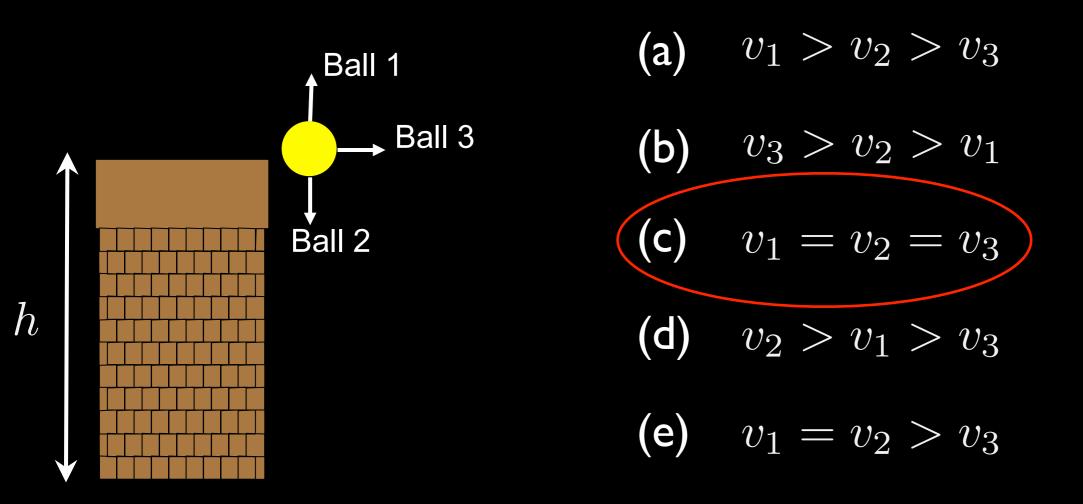
What height is needed to reached the speed 2v?

Energy conservation: $\Delta U_{top} = K_{bottom}$

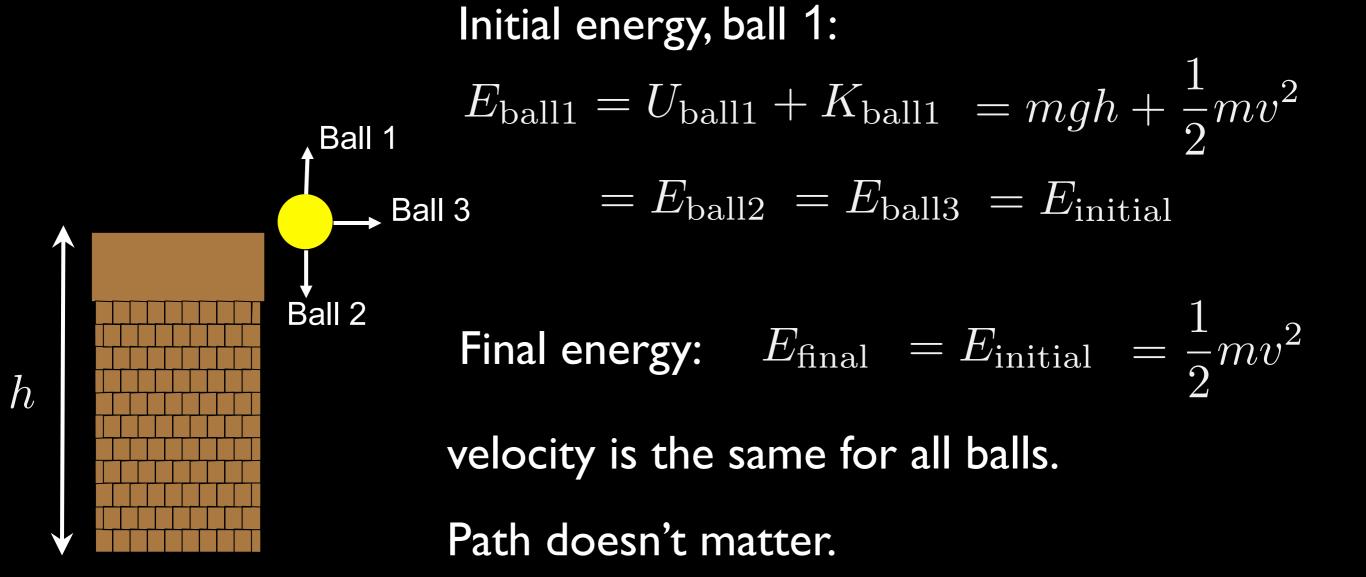




3 balls of equal mass are fired at equal speeds from the same height. Ball 1 is fired up, ball 2 down and ball 3 horizontally. Rank their speeds from big to small before they hit the ground. (ignore friction / drag)

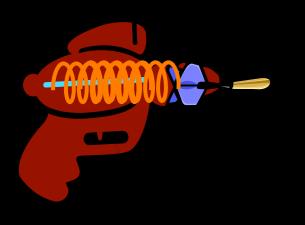


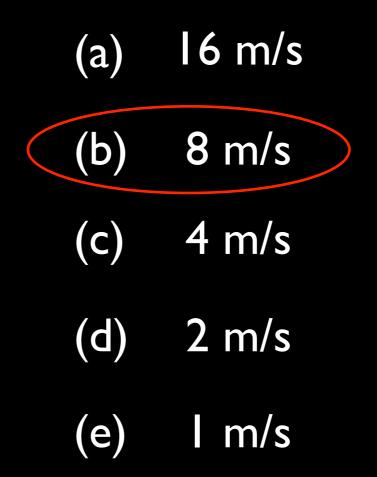
- 3 balls of equal mass are fired at equal speeds from the same height. Ball 1 is fired up, ball 2 down and ball 3 horizontally.
- Rank their speeds from big to small before they hit the ground.



A spring-loaded gun shoots a ball with speed 4 m/s.

If the spring is compressed twice as far, the ball's speed will be....

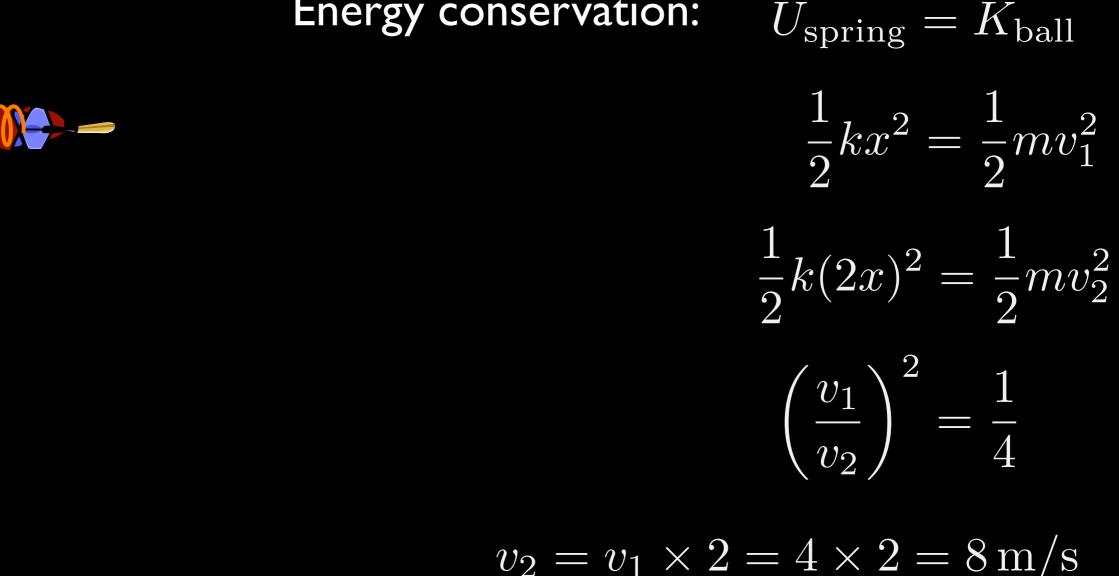




A spring-loaded gun shoots a ball with speed 4 m/s.

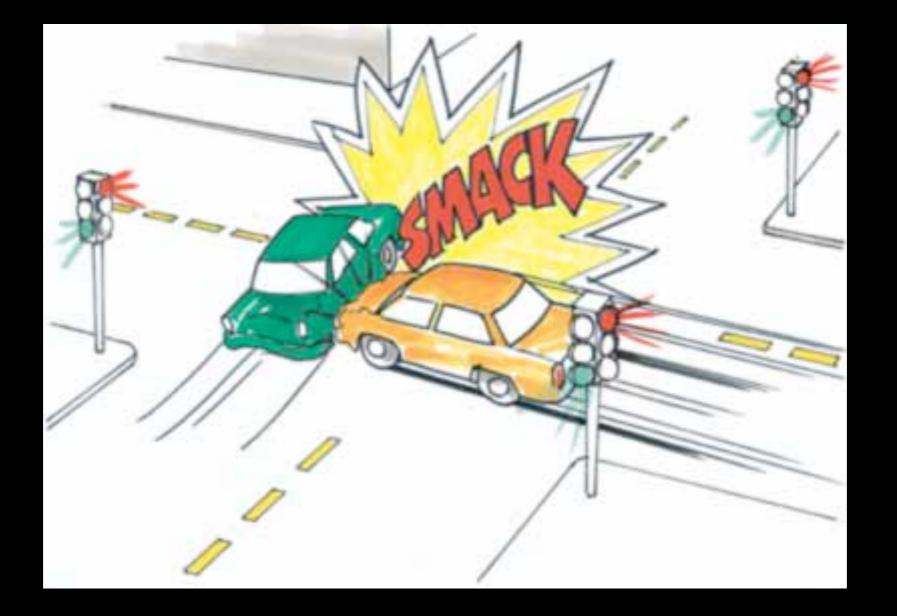
If the spring is compressed twice as far, the ball's speed will be....

Last lecture: review



Energy conservation:

This lecture:





In lecture 4:

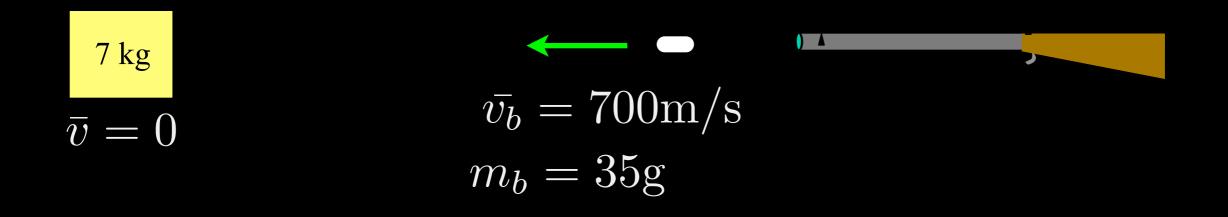
Newton's 2nd law:
$$ar{F}_{
m net} = rac{dar{p}}{dt} = mar{a}$$

where the momentum, $\bar{p}=m\bar{v}$

If
$$\bar{F}_{net} = 0$$
, $\bar{p} = constant$ Conservation of linear momentum

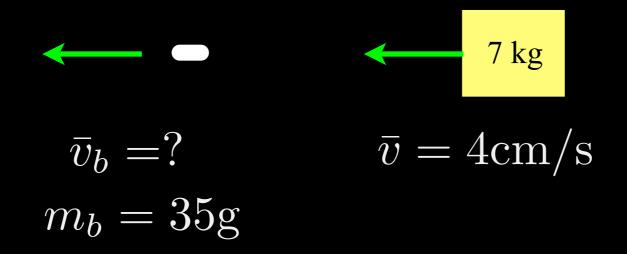
"If there is no net external force on a system, the total momentum is constant"





A gun fires a bullet into butter.

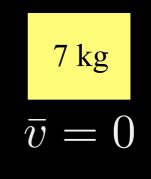
The bullet travels through the butter, slows and pushes the butter to the right on a frictionless surface.



What is the final speed of the bullet?

Total momentum before:

 $\bar{p}_{before} = m\bar{v} - m_b \bar{v}_b$ butter bullet



 $\bar{v_b} = 700 \text{m/s}$ $m_b = 35 \text{g}$

Total momentum before:

 $\bar{p}_{\text{before}} = m\bar{v} + m_b\bar{v}_b$

= (7 kg)(0) + (0.035 kg)(700 m/s)= 24.5 kgm/s

$$7 \, \mathrm{kg}$$
 $ar{v} = 0$

$$\bar{v_b} = 700 \text{m/s}$$

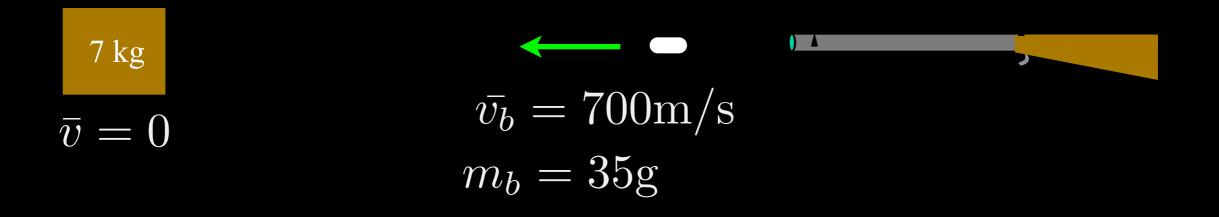
 $m_b = 35 \text{g}$

Example

Total momentum after:

 $\bar{p}_{after} = (7 \text{ kg})(0.04 \text{ m/s}) + (0.035 \text{ kg})\bar{v}_b$ $\bar{v}_b = ? \qquad \bar{v} = 4 \text{ cm/s}$ $= 0.28 + 0.035 v_b \qquad m_b = 35 \text{ g}$

 $\bar{p}_{before} = \bar{p}_{after} \rightarrow 24.5 = 0.28 + 0.035 v_b$ $v_b = 692 \text{m/s}$

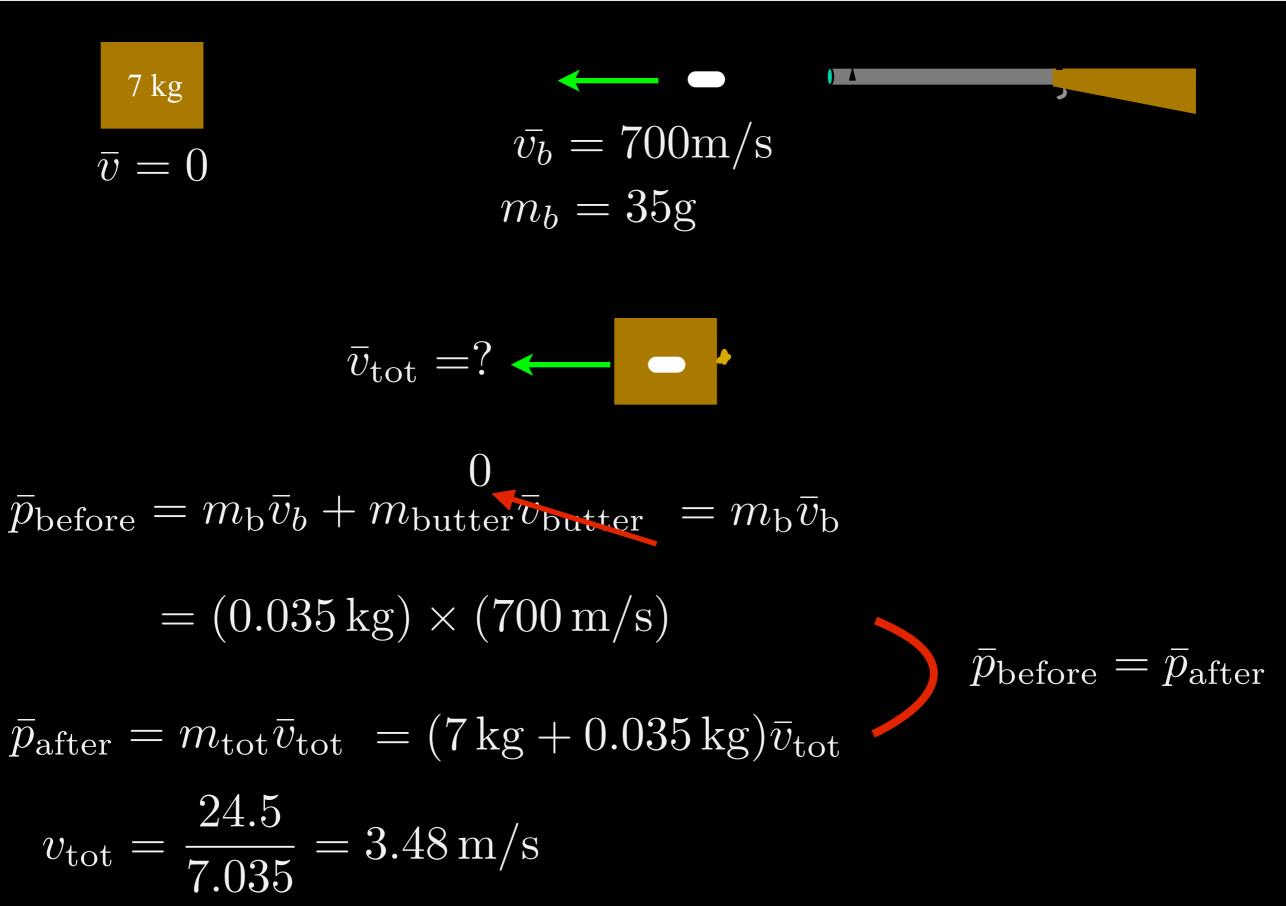


Same problem, but butter is now wood.

The bullet stops in the wood and they move together on a frictionless surface.

$$\bar{v}_{\rm tot} = ? \longleftarrow$$

(a) 3.48 m/s (b) 4 cm/s (c) 700 m/s (d) 3.5 m/s



A popcorn kernal at rest in a hot pan bursts into two pieces, with masses 91-mg and 64-mg.

The more massive piece moves horizontally at 47 cm/s. What is the velocity of the 2nd piece?

(a) 33 cm/s

(b) 67 cm/s

(c) -67 cm/s

(d) -33 cm/s





A popcorn kernal at rest in a hot pan bursts into two pieces, with masses 91-mg and 64-mg.

The more massive piece moves horizontally at 47 cm/s. What is the velocity of the 2nd piece?

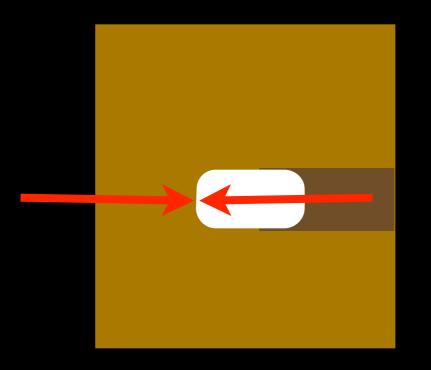
 $\bar{p}_{before} = m_{tot} \bar{v}_{tot}$ $= (91 \text{ mg} + 64 \text{ mg}) \times 0$ $\bar{p}_{after} = m_1 \bar{v}_1 + m_2 \bar{v}_2$ $= (91 \text{ mg})(47 \text{ cm/s}) + (64 \text{ mg}) \bar{v}_2$ $\bar{v}_2 = -\frac{(91 \text{ mg})(47 \text{ cm/s})}{64 \text{ mg}} = -67 \text{ cm/s}$

 $\bar{p}_{\text{before}} = \bar{p}_{\text{after}}$



Why does this work?

What about the other forces in the system?

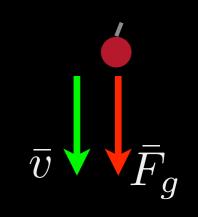


Because of Newton's 3rd law, internal forces are equal and opposite.

Therefore, the change in momentum is equal and opposite.

So $\Delta p = 0$ and momentum is conserved (if no external forces)

- An apple is dropped from a height. After t seconds, its velocity is v. Which of the following is true?
 - (a) the apple's momentum is conserved
 - (b) the Earth's momentum is conserved
 - (c) the apple + the Earth's momentum is conserved
 - (d) all the above



An apple is dropped from a height. After t seconds, its velocity is v. Which of the following is true?

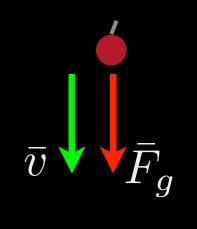
(a) the apple's momentum is conserved initial final

initialfinal $\bar{p}_{apple,i} = 0.0$ $\bar{p}_{apple,f} = mv$

 $\bar{p}_{\mathrm{apple,i}} \neq \bar{p}_{\mathrm{apple,f}}$

Gravity is an external force on the apple.

Therefore, the apple's momentum alone is not conserved.



An apple is dropped from a height. After t seconds, its velocity is v.

 \overline{v}

Which of the following is true?

From Newton's 3rd law, the apple also exerts a force on the Earth,

causing a (tiny!) velocity change.

Therefore: $\bar{p}_{\text{Earth,i}} \neq \bar{p}_{\text{Earth,f}}$

The Earth's momentum alone is not conserved.

An apple is dropped from a height. After t seconds, its velocity is v.

system

Which of the following is true?

(c) the apple + the Earth's momentum is conserved

If our system includes both Earth and apple, gravity is an internal force.

$$\bar{p}_{\text{total}} = M_{\text{Earth}} v_{\text{Earth}} + m_{\text{apple}} v_{\text{apple}}$$
$$= 0$$

$$\bar{p}_{\text{total,i}} = \bar{p}_{\text{total,f}}$$

Momentum is a vector: $ar{p}$

- \overline{v} and \overline{p} point in the same direction.
- SI unit: kgm/s
- Momentum is conserved (like energy) if there is no external force
- A net force ($ar{F}_{
 m net}
 eq 0$) is required to change a body's momentum Momentum is proportional to mass and velocity: $ar{p}=mar{v}$



Therefore, a big and slow object can have the same momentum as a small and fast object





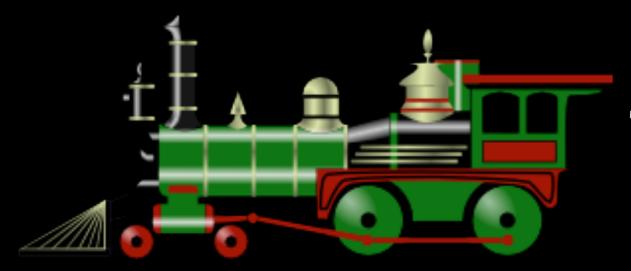
Facts

Equivalent momentum:



Bus: m = 9000 kg; v = 16 m/s $p = 1.44 \cdot 10^5 \text{ kg} \cdot \text{m/s}$ Car: m = 1800 kg; v = 80 m/s $p = 1.44 \cdot 10^5 \text{ kg} \cdot \text{m/s}$





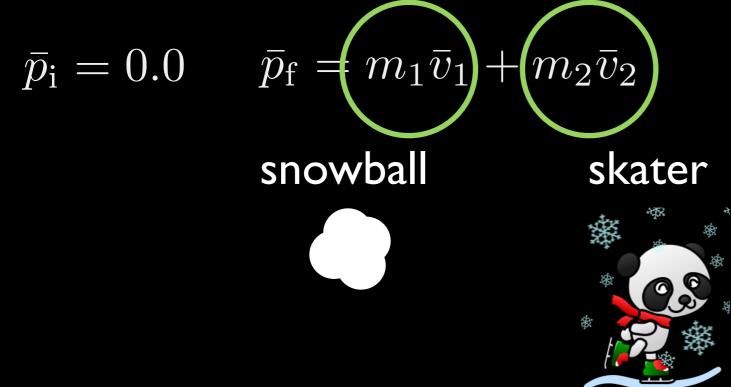
Train: $m = 3.6 \cdot 10^4$ kg; v = 4 m/s $p = 1.44 \cdot 10^5$ kg \cdot m/s

 $\frac{d\bar{p}}{dt}$

The same force would be needed to stop all three. $ar{F}_{
m net}$

Since \overline{p} is a vector, 2D problems can be solved with components: <u>Example</u>:

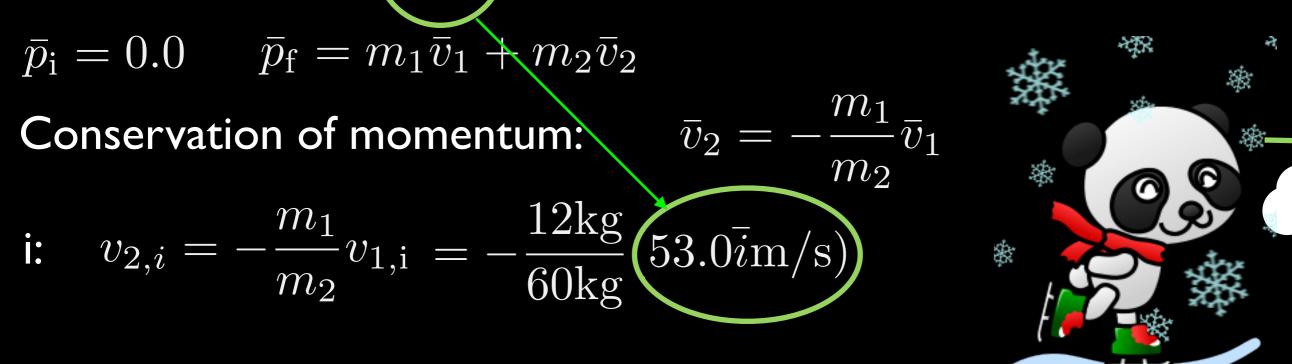
A 60-kg skater, at rest on a frictionless ice, tosses a 12-kg snowball with velocity $\bar{v} = 53.0\bar{i} + 14.0\bar{j}$ m/s. Find the skater's velocity.





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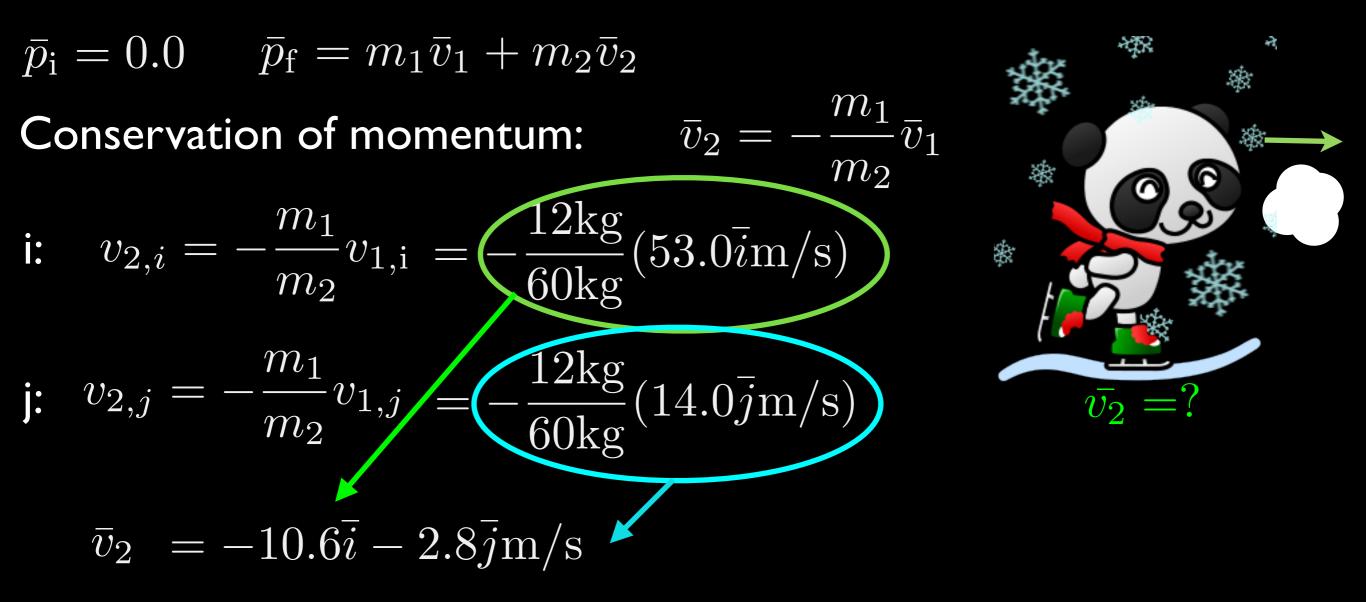
A 60-kg skater, at rest on a frictionless ice, tosses a 12-kg snowball with velocity $\bar{v} = 53.0\bar{i} + 14.0\bar{j}$ m/s. Find the skater's velocity.

$$\bar{p}_{i} = 0.0 \quad \bar{p}_{f} = m_{1}\bar{v}_{1} + m_{2}\bar{v}_{2}$$
Conservation of momentum: $\bar{v}_{2} = -\frac{m_{1}}{m_{2}}\bar{v}_{1}$
i: $v_{2,i} = -\frac{m_{1}}{m_{2}}v_{1,i} = -\frac{12\text{kg}}{60\text{kg}}(53.0\bar{i}\text{m/s})$
j: $v_{2,j} = -\frac{m_{1}}{m_{2}}v_{1,j} = -\frac{12\text{kg}}{60\text{kg}}(14.0\bar{j}\text{m/s})$



Since \overline{p} is a vector, 2D problems can be solved with components: <u>Example</u>:

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Three types of collisions:

(I) Elastic

K and p are conserved. Nothing sticks together. p: $m_1 \overline{v}_{1,i} + m_2 \overline{v}_{2,i} = m_1 \overline{v}_{1,f} + m_2 \overline{v}_{2,f}$

K:
$$\frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2 = \frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2$$

(2) Inelastic

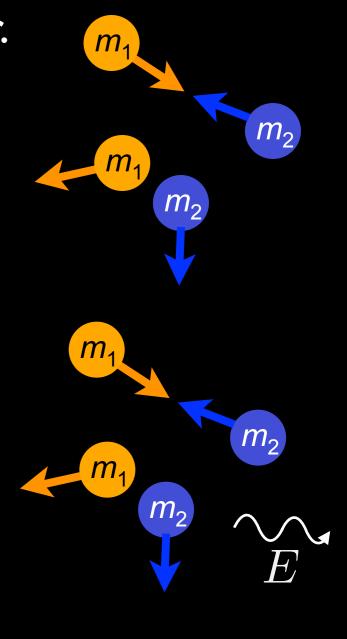
Only p is conserved. Nothing sticks together.

p: $m_1 \bar{v}_{1,i} + m_2 \bar{v}_{2,i} = m_1 \bar{v}_{1,f} + m_2 \bar{v}_{2,f}$

(3) Totally inelastic

Only p is conserved. Objects sticks together.

p: $m_1 \bar{v}_1 + m_2 \bar{v}_2 = (m_1 + m_2) \bar{v}_f$





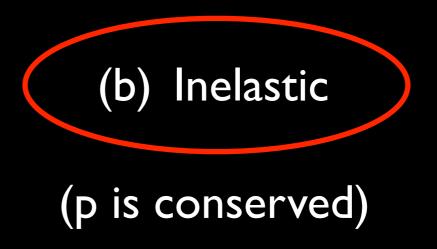
 m_2

Quiz

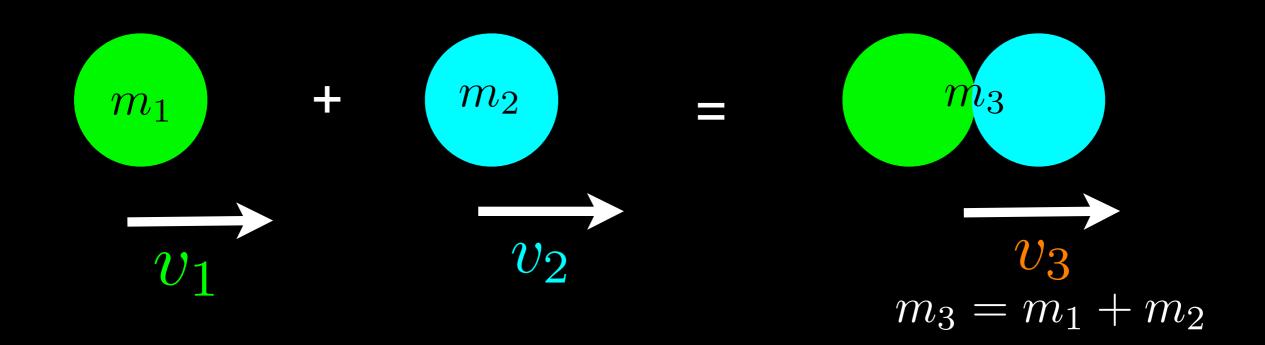
In real life, most collisions are:

(a) Elastic

(K and p are conserved)



Totally inelastic: ID

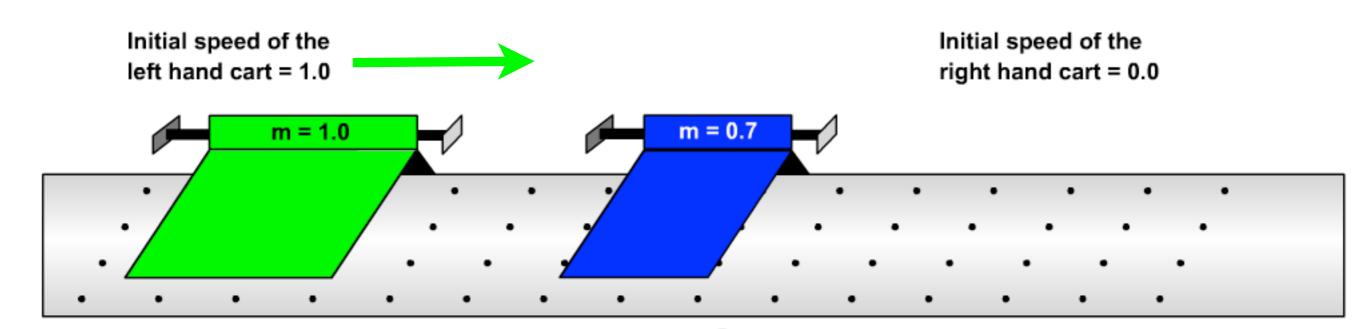


Conservation of momentum:

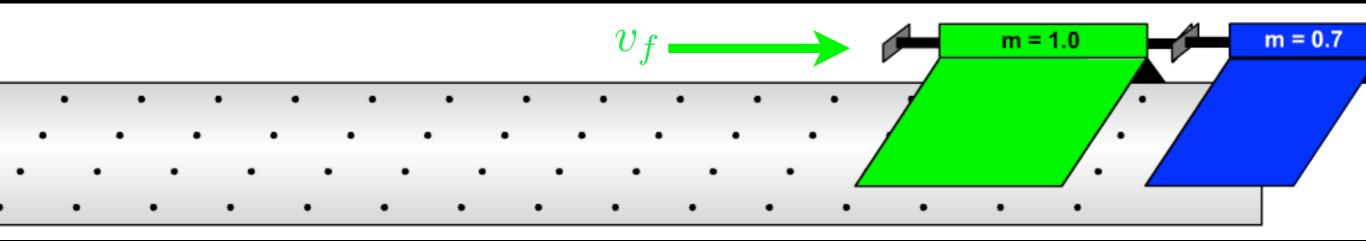
 $m_1v_1 + m_2v_2 = (m_1 + m_2)v_3$

Quiz

Inelastic collision ID:



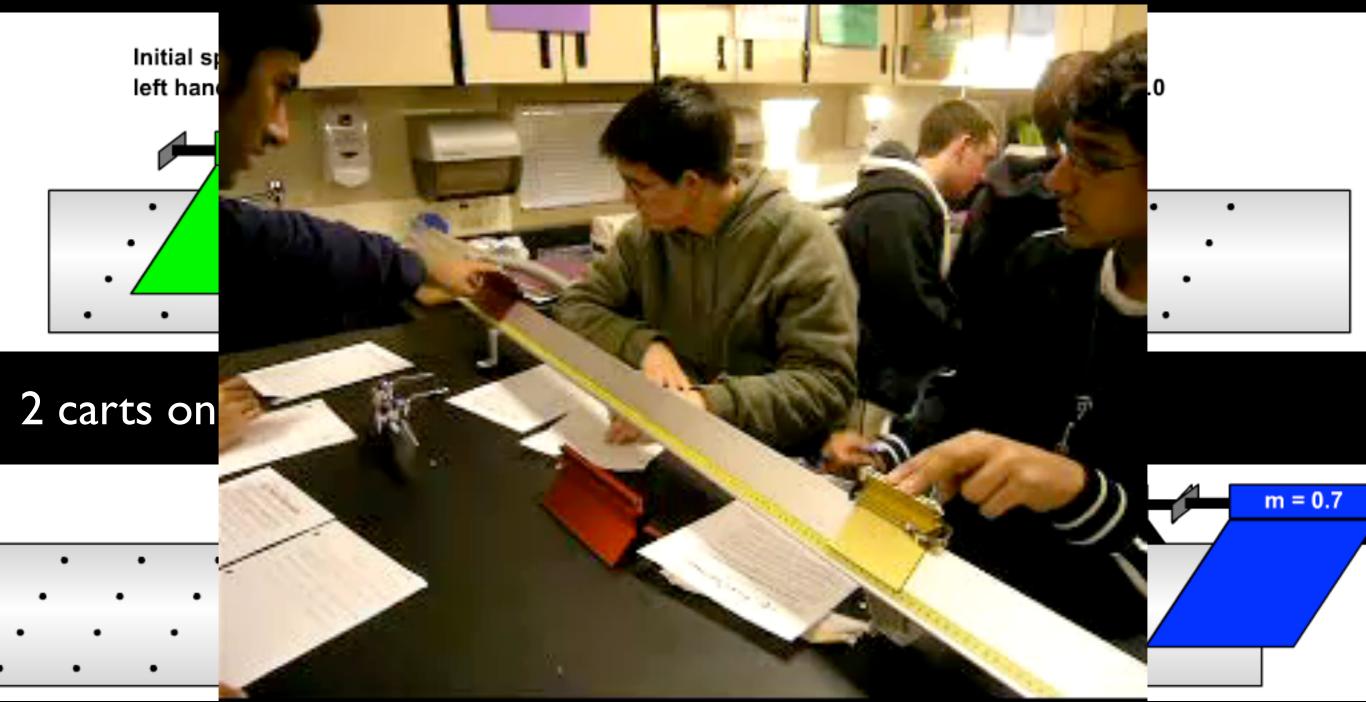
2 carts on frictionless track collide and stick together.



what is their combined velocity v_f ?



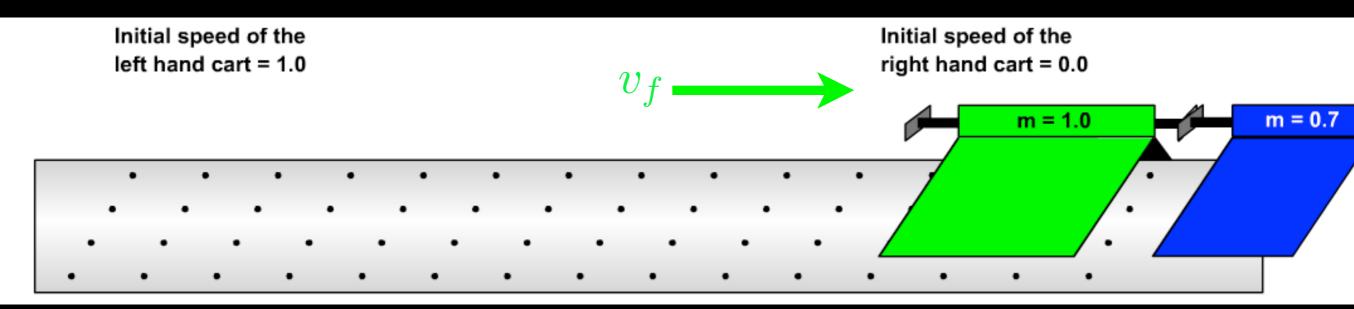
Inelastic collision ID:



what is their combined velocity v_f ?

Quiz

Inelastic collision ID:



what is their combined velocity v_f ?

(a) 0.588

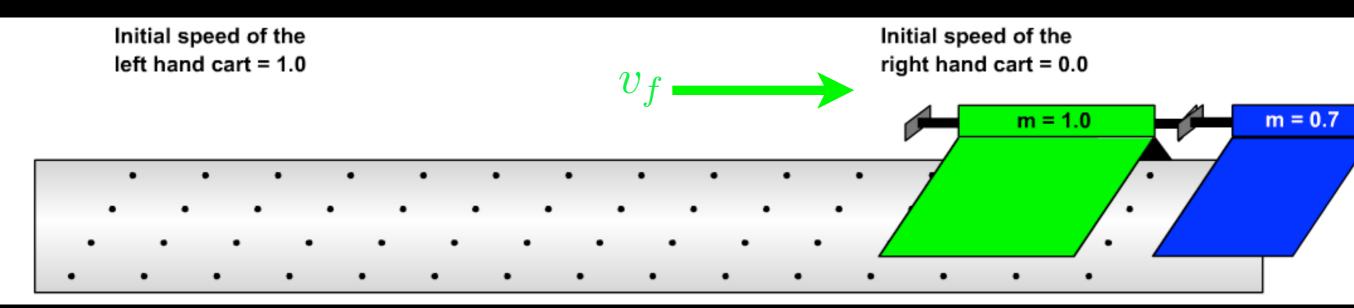
(b) I.0

(c) 1.43

(d) 0.5

Quiz

Inelastic collision ID:

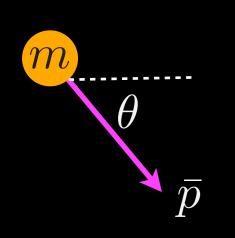


what is their combined velocity v_f ? $\bar{p}_{before} = m_L \bar{v}_L + m_R \bar{v}_R = 1 \times 1 + 0.7 \times 0$

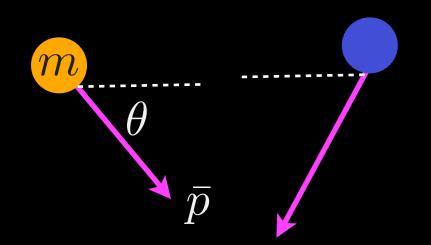
 $\bar{p}_{after} = m_{tot} \bar{v}_{tot} = 1.7 \times \bar{v}_{tot}$

$$\bar{v}_{\rm tot} = \frac{1}{1.7} = 0.588$$

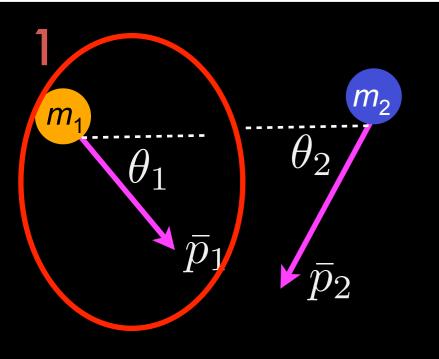
 $\bar{p}_{\text{before}} = \bar{p}_{\text{after}}$



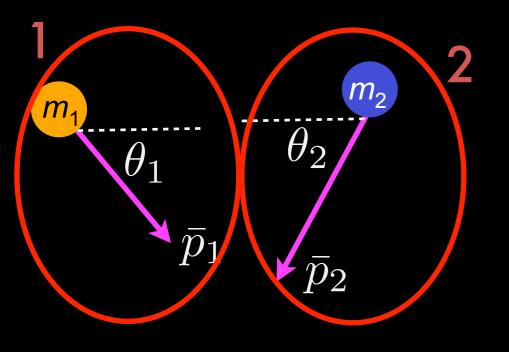
- $p_x = mv_x = mv\cos\theta$
- $p_y = mv_y = mv\sin\theta$



- $p_x = mv_x = mv\cos\theta$
- $p_y = mv_y = mv\sin\theta$



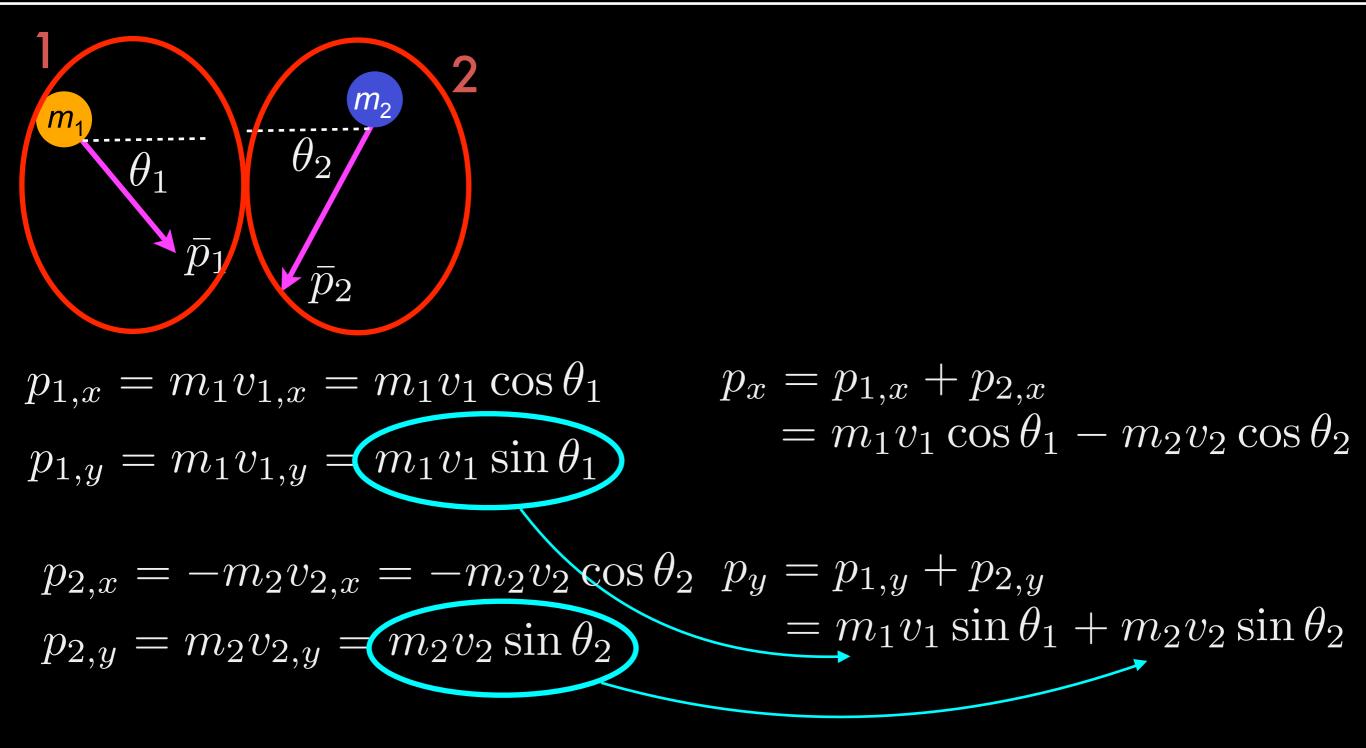
 $\overline{p_{1,x}} = \overline{m_1 v_{1,x}} = \overline{m_1 v_1} \cos \theta_1$ $p_{1,y} = m_1 v_{1,y} = m_1 v_1 \sin \theta_1$



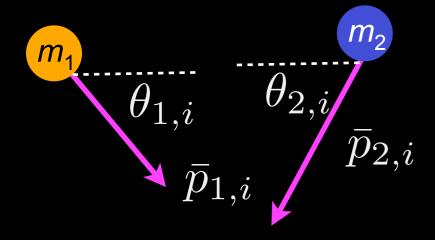
 $p_{1,x} = m_1 v_{1,x} = m_1 v_1 \cos \theta_1$ $p_{1,y} = m_1 v_{1,y} = m_1 v_1 \sin \theta_1$

 $p_{2,x} = -m_2 v_{2,x} = -m_2 v_2 \cos \theta_2$ $p_{2,y} = m_2 v_{2,y} = m_2 v_2 \sin \theta_2$

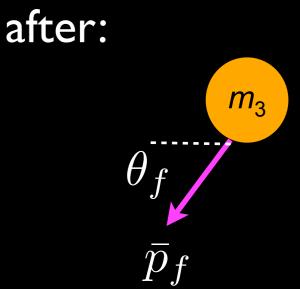
 m_2 m_1 $heta_2$ $heta_1$ \bar{p}_1 \bar{p}_2 $p_{1,x} = m_1 v_{1,x} = m_1 v_1 \cos \theta_1$ $p_x = p_{1,x} + p_{2,x}$ $= m_1 v_1 \cos \theta_1 - m_2 v_2 \cos \theta_2$ $p_{1,y} = m_1 v_{1,y} = m_1 v_1 \sin \theta_1$ $p_{2,x} = -m_2 v_{2,x} = -m_2 v_2 \cos \theta_2$ $p_{2,y} = m_2 v_{2,y} = m_2 v_2 \sin \theta_2$



before:



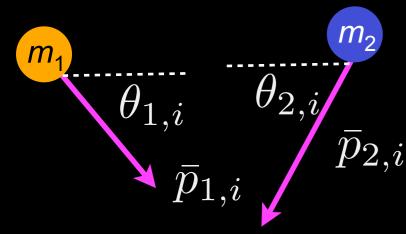




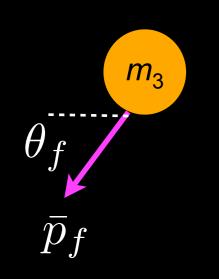
 $p_x = p_{1,x,i} + p_{2,x,i}$ $= m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i}$ $p_x = -m_3 v_f \cos \theta_f$

 $p_y = p_{1,y,i} + p_{2,y,i}$ $= m_1 v_{1,i} \sin \theta_{1,i} + m_2 v_{2,i} \sin \theta_{2,i}$ $p_y = m_3 v_f \sin \theta_f$

before:



after:



Conservation of momentum:

$$p_x = m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i}$$
$$p_y = m_1 v_{1,i} \sin \theta_{1,i} + m_2 v_{2,i} \sin \theta_{2,i}$$

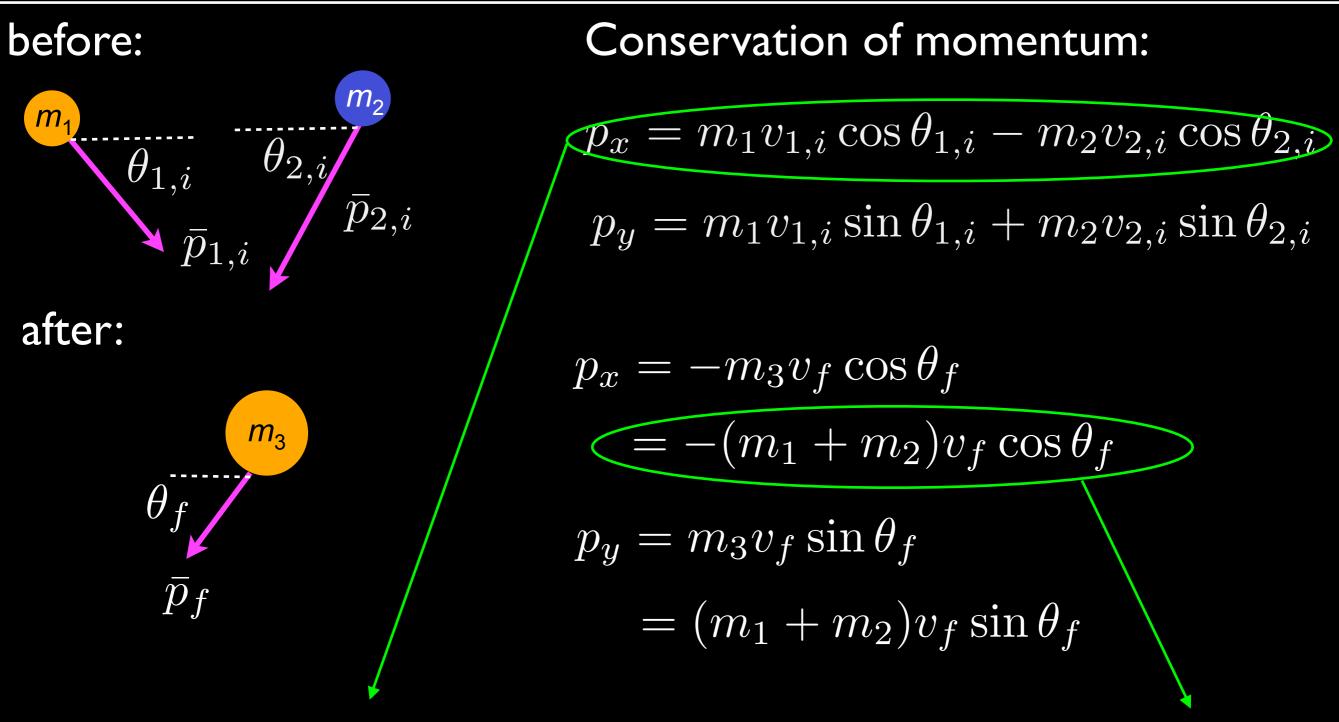
$$p_x = -m_3 v_f \cos \theta_f$$

= $-(m_1 + m_2) v_f \cos \theta_f$
$$p_y = m_3 v_f \sin \theta_f$$

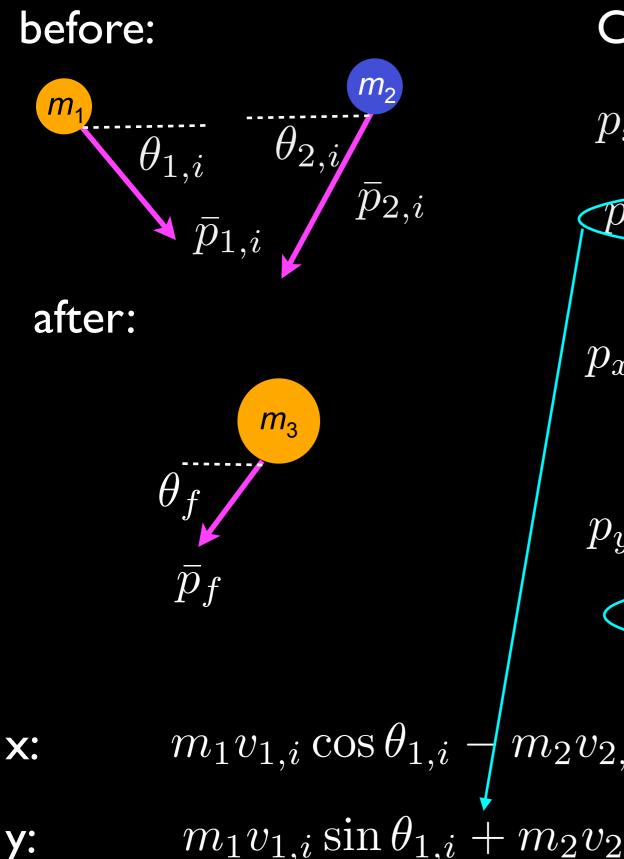
= $(m_1 + m_2) v_f \sin \theta_f$

.1

- $p_{x,\text{initial}} = p_{x,\text{final}}$ Х:
- $p_{y,\text{initial}} = \overline{p_{y,\text{final}}}$ У:



x: $m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i} = -(m_1 + m_2) v_f \cos \theta_f$



Conservation of momentum: $p_x = m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i}$ $p_y = m_1 v_{1,i} \sin \theta_{1,i} + m_2 v_{2,i} \sin \theta_{2,i}$ $p_x = -m_3 v_f \cos \theta_f$ $= -(m_1 + m_2)v_f \cos\theta_f$ $\overline{p}_y = \overline{m_3} v_f \sin \theta_f$ $(m_1 + m_2)v_f \sin \theta_f$ $m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i} = -(m_1 + m_2) v_f \cos \theta_f$ $m_1 v_{1,i} \sin \theta_{1,i} + m_2 v_{2,i} \sin \theta_{2,i} = (m_1 + m_2) v_f \sin \theta_f$

A neutron (mass I u) strikes a deutron (mass 2 u) and they combine to form a tritium nucleus.

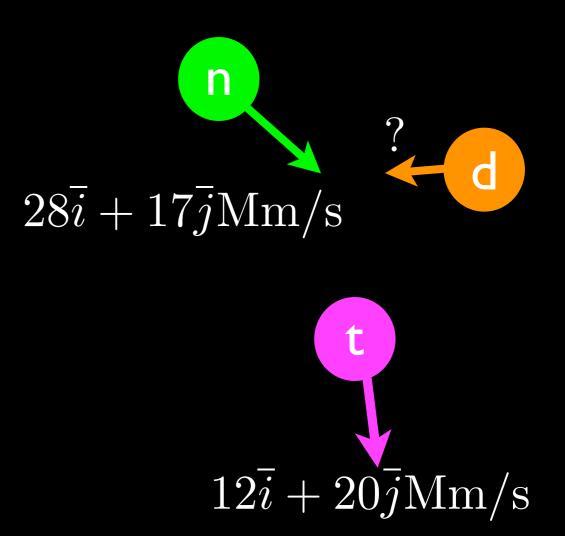
If the neutron's initial velocity was $28\overline{i} + 17\overline{j}$ Mm/s

and the tritium's final velocity is $12\overline{i} + 20\overline{j} \mathrm{Mm/s}$

what is the deutron's velocity?

- (a) $40\overline{i} 37\overline{j}$ Mm/s
- (b) $32\bar{i} + 38.5\bar{j}$ Mm/s
- (c) $16\overline{i} 3\overline{j}$ Mm/s

(d) $4\bar{i} + 21.5\bar{j}$ Mm/s



Quiz

Quiz

 $21.5\hat{j}$ Mm/s



Atomic mass unit: $1u = 1.67 \times 10^{-27} \text{ kg}$

d = 1 proton + 1 neutron

 $\frac{1}{28\overline{i} + 17\overline{j}} \text{Mm/s} \stackrel{?}{\sim} \mathbf{d}$

$$\bar{p}_{before} = m_n \bar{v}_n + m_d \bar{v}_d \qquad \qquad \bar{p}_{before} = \bar{p}_{after} \qquad \qquad \mathbf{\vec{p}}_{after} = m_t \bar{v}_t \qquad \qquad \mathbf{\vec{p}}_{after} = \bar{p}_{after} = \bar{p}_{after} = \bar{p}_{after} = \bar{p}_{after} = \bar{p}_{after} = \bar{p}_{after} \qquad \qquad \qquad \mathbf{\vec{p}}_{after} = \bar{p}_{after} = \bar{p}$$

x:
$$\bar{v}_{d,x} = \frac{(3u \times 12) - (u \times 28)}{2u} = 4 \text{ Mm/s}$$

y: $\bar{v}_{d,y} = \frac{(3u \times 20) - (u \times 17)}{2u} = 21.5 \text{ Mm/s}$

Quiz

Just for interest:

Atomic mass unit: $1u = 1.67 \times 10^{-27} \text{ kg}$

d = 1 proton + 1 neutron

n $28\overline{i} + 17\overline{j}$ Mm/s

t $12\overline{i} + 20\overline{j} \text{Mm/s}$

$$\overline{v}_d = \frac{m_t \overline{v}_t - m_n \overline{v}_n}{m_d}$$

$$=\frac{3u(12\hat{i}+20\hat{j})-u(28\hat{i}+17\hat{j})}{2u} = 4\bar{i}+21.5\bar{j}\,\mathrm{Mm/s}$$

Elastic: ID

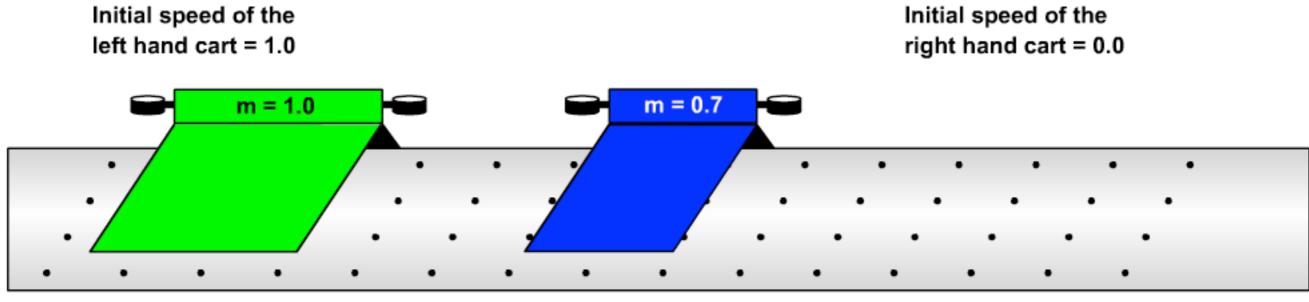


Conservation of momentum, p:

 $m_1 v_{1,i} + m_2 v_{2,i} = m_1 v_{1,f} + m_2 v_{2,f}$

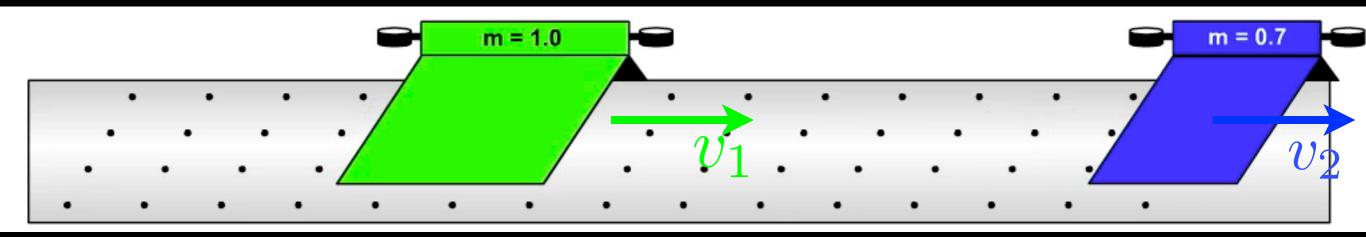
Conservation of kinetic energy, K: $\frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2 = \frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2$

Elastic collision ID:



007

2 carts on frictionless track collide in an elastic collision



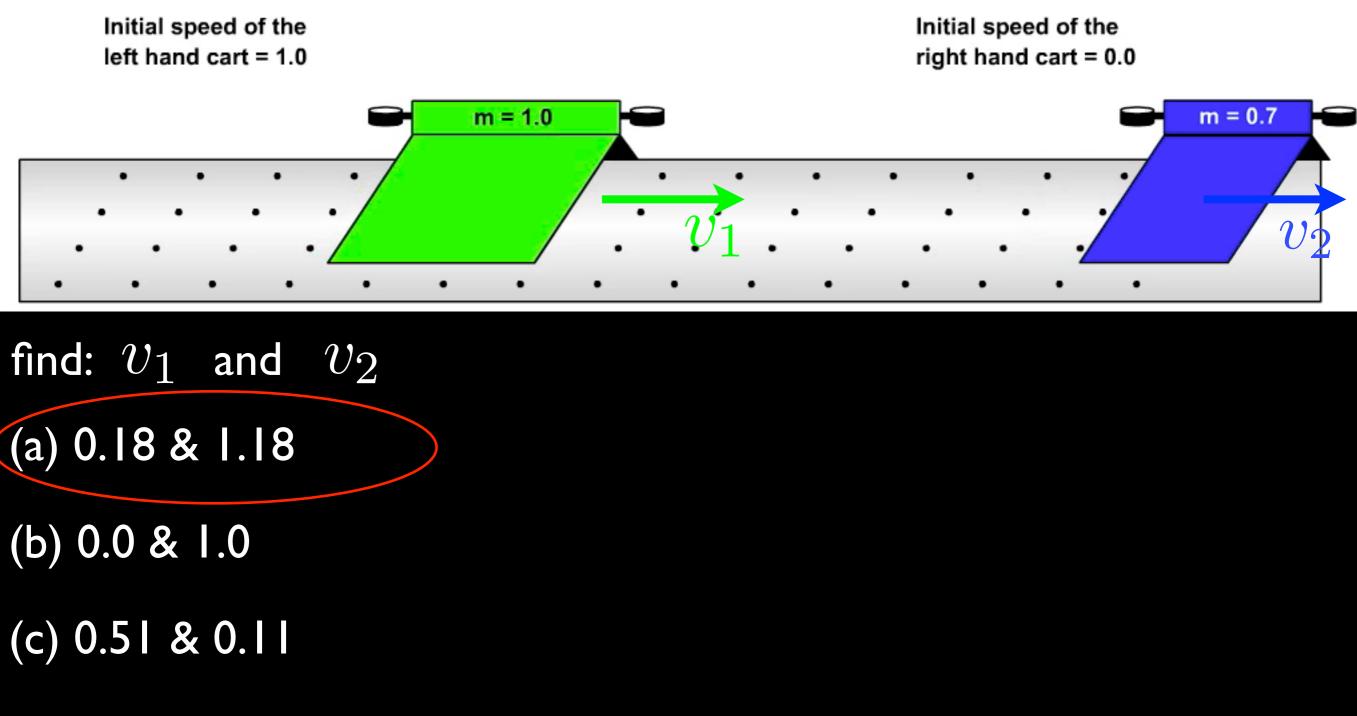
find: v_1 and v_2

Elastic collision ID:



find: v_1 and v_2

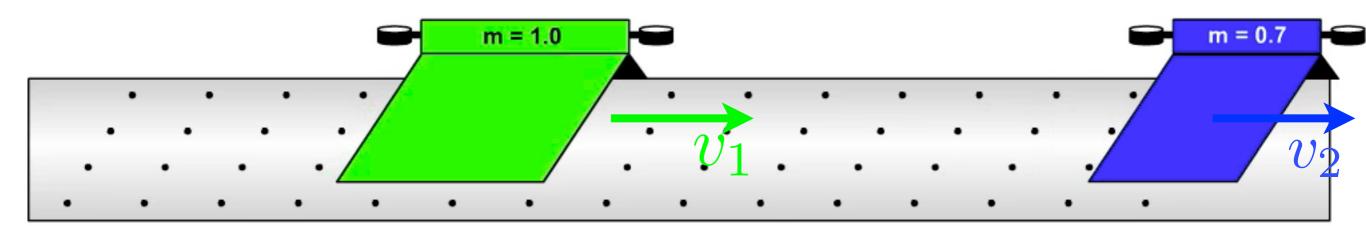
Elastic collision ID:



(d) 0.5 & -0.5

Elastic collision ID: find: v_1 and v_2

Initial speed of the left hand cart = 1.0 Initial speed of the right hand cart = 0.0



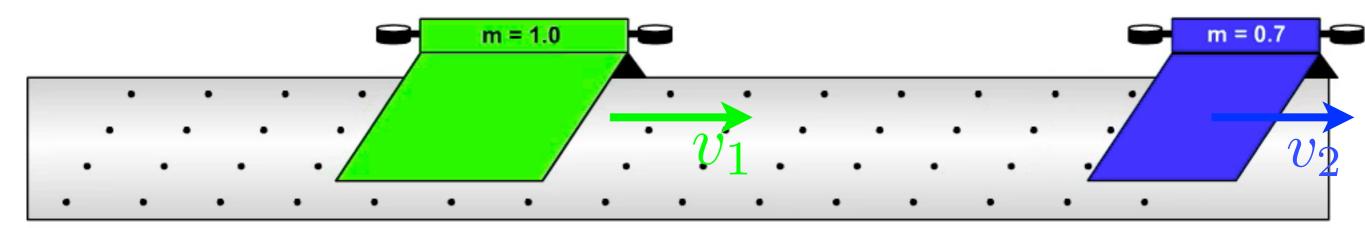
 $\bar{p}_{\text{before}} = m_L \bar{v}_{L,1} + m_R \bar{v}_{R,1} = 1 \times 1 + 0.7 \times 0$

 $\bar{p}_{after} = m_L \bar{v}_{L,2} + m_R \bar{v}_{R,2} = 1 \times \bar{v}_{L,2} + 0.7 \times \bar{v}_{R,2}$

 $K_{\text{before}} = \frac{1}{2} m_L \bar{v}_{L,1}^2 + \frac{1}{2} m_R \bar{v}_{R,1}^2 = \frac{1}{2} \times 1 \times 1^2 + 0$ $K_{\text{after}} = \frac{1}{2} m_L \bar{v}_{L,2}^2 + \frac{1}{2} m_R \bar{v}_{R,2}^2 = \frac{1}{2} 1 \bar{v}_{L,2}^2 + \frac{1}{2} 0.7 \bar{v}_{R,2}^2$

Elastic collision ID: find: v_1 and v_2

Initial speed of the left hand cart = 1.0 Initial speed of the right hand cart = 0.0



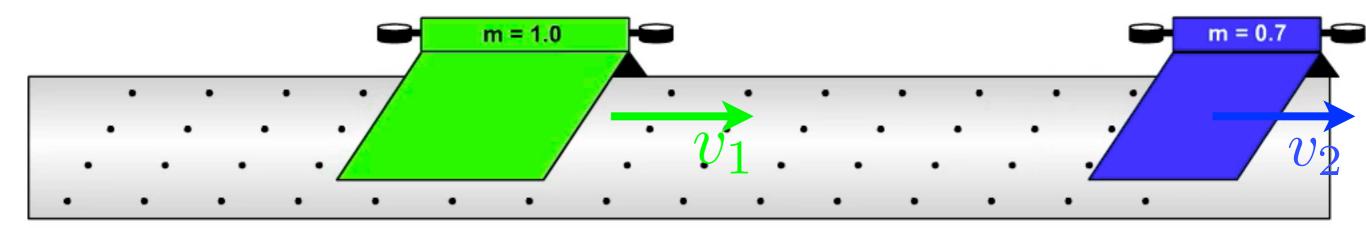
 $\bar{p}_{\text{before}} = \bar{p}_{\text{after}}$

$$1 = \bar{v}_{L,2} + 0.7 \bar{v}_{R,2} \longrightarrow \bar{v}_{L,2} = 1 - 0.7 \bar{v}_{R,2}$$
$$K_{\text{before}} = K_{\text{after}}$$

$$\frac{1}{2} = \frac{1}{2}\bar{v}_{L,2}^2 + \frac{1}{2}0.7\bar{v}_{R,2}^2 \longrightarrow 1 = \bar{v}_{L,2}^2 + 0.7\bar{v}_{R,2}^2$$

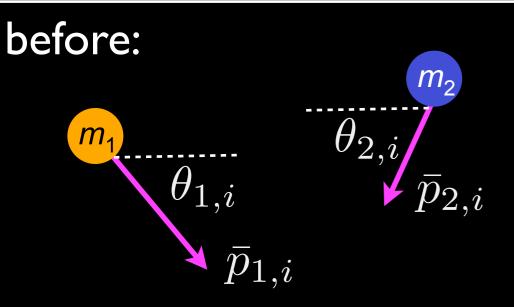
Elastic collision ID: find: v_1 and v_2

Initial speed of the left hand cart = 1.0 Initial speed of the right hand cart = 0.0



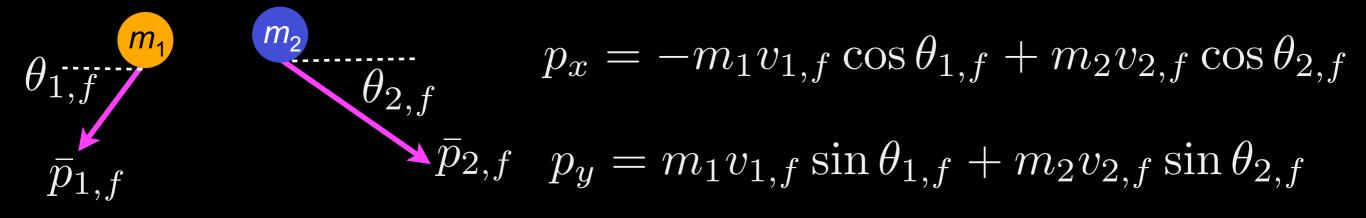
Combining:

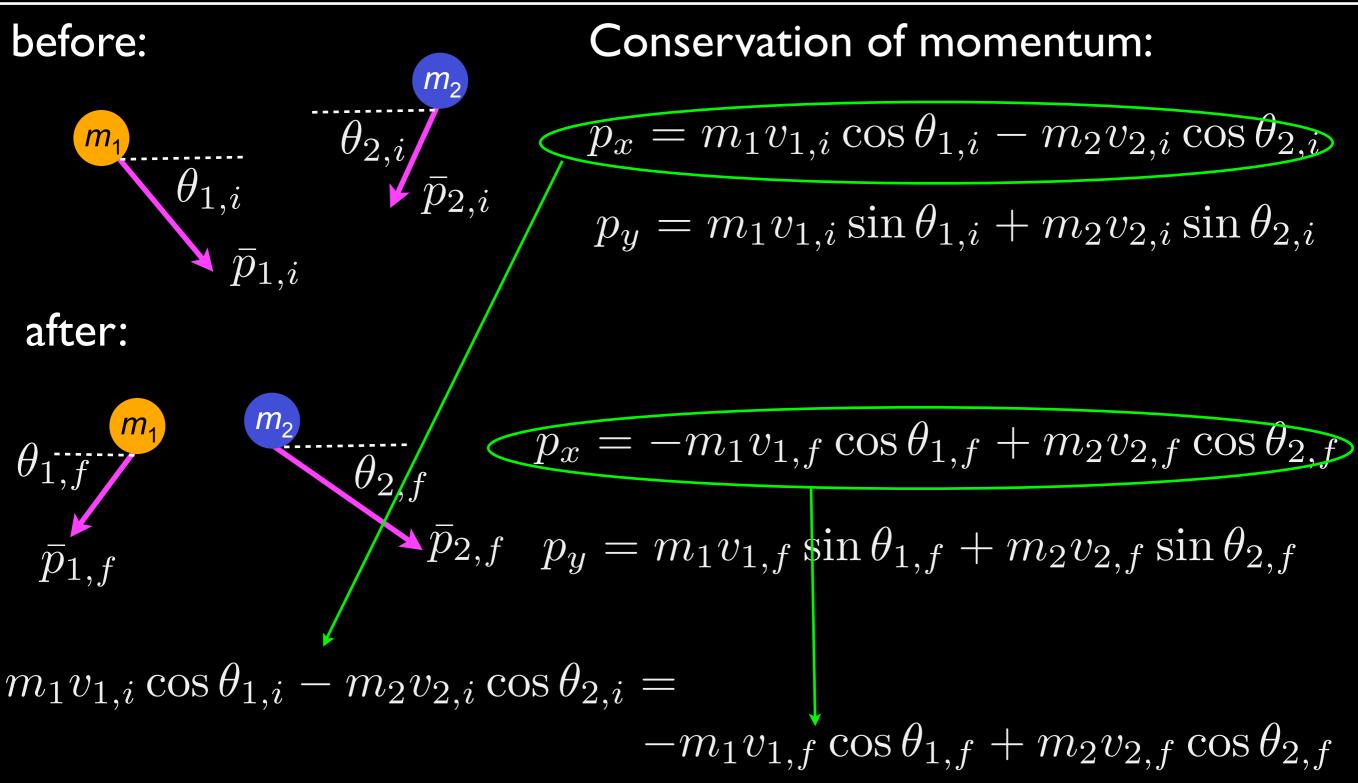
IIIIlai

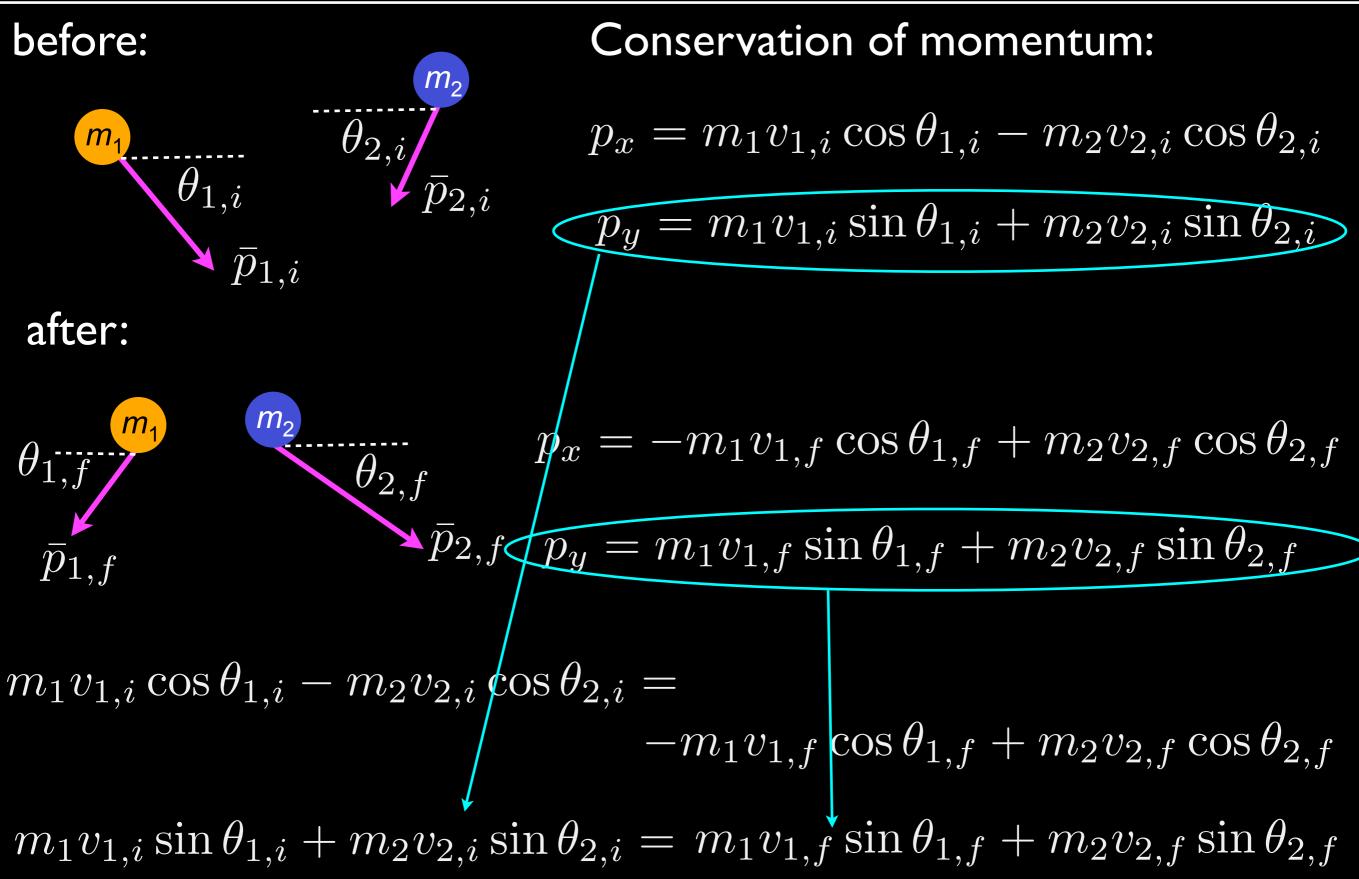


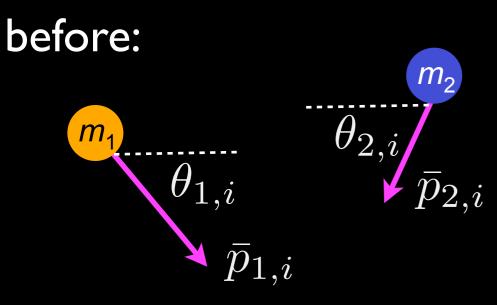
Conservation of momentum: $p_x = m_1 v_{1,i} \cos \theta_{1,i} - m_2 v_{2,i} \cos \theta_{2,i}$ $p_y = m_1 v_{1,i} \sin \theta_{1,i} + m_2 v_{2,i} \sin \theta_{2,i}$

after:





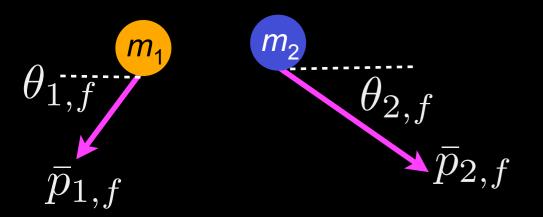




Conservation of kinetic energy:

 $\frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2$

after:



 $\frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2$

$$\frac{1}{2}m_1v_{1,i}^2 + \frac{1}{2}m_2v_{2,i}^2 = \frac{1}{2}m_1v_{1,f}^2 + \frac{1}{2}m_2v_{2,f}^2$$

Example

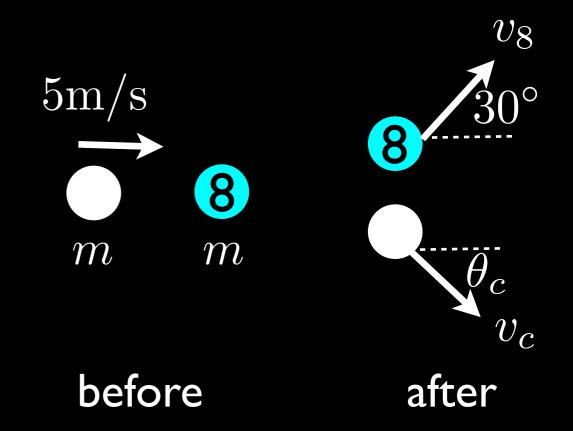
In a pool game, the cue ball, with an initial speed of 5 m/s, makes and elastic collision with the 8-ball, which is initially at rest.

After the collision, the 8-ball moves at an angle of 30° with the original direction of the cue ball.

(a) find the direction of motion of the cue ball

(b) speed of each ball

Assume balls are of equal mass.



Example

Conservation of momentum:

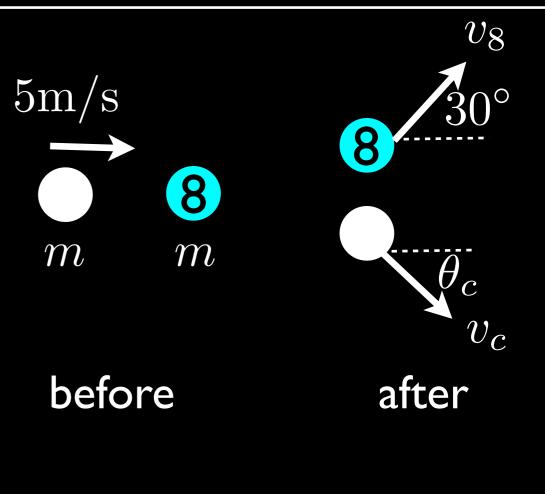
- X: $5m = mv_8 \cos 30 + mv_c \cos \theta_c$
- Y: $0 = mv_8 \sin 30 + mv_c \sin \theta_c$

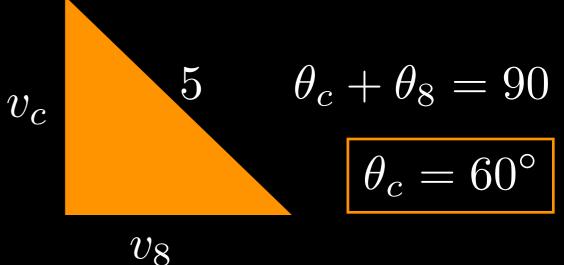
Conservation of kinetic energy:

$$\frac{1}{2}m5^2 = \frac{1}{2}mv_8^2 + \frac{1}{2}mv_c^2$$

when mass is equal:

 $5^{2} = v_{8}^{2} + v_{c}^{2}$ Fythagorus: right-angled triangle equation





From:

 $0 = mv_8 \sin 30 + mv_c \sin \theta_c$

 $v_8 = v_c \frac{\sin 60}{\sin 30}$

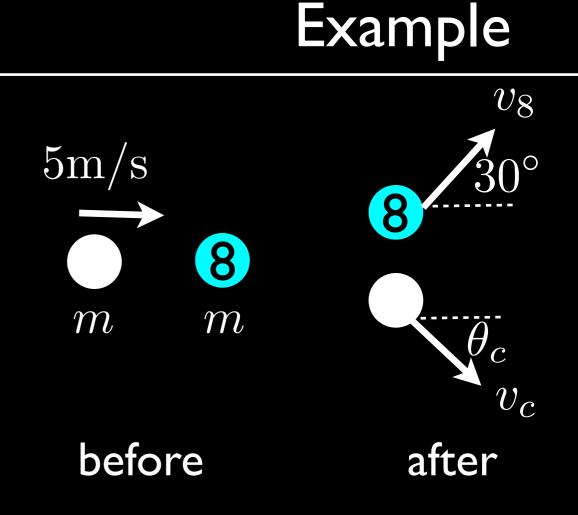
From:

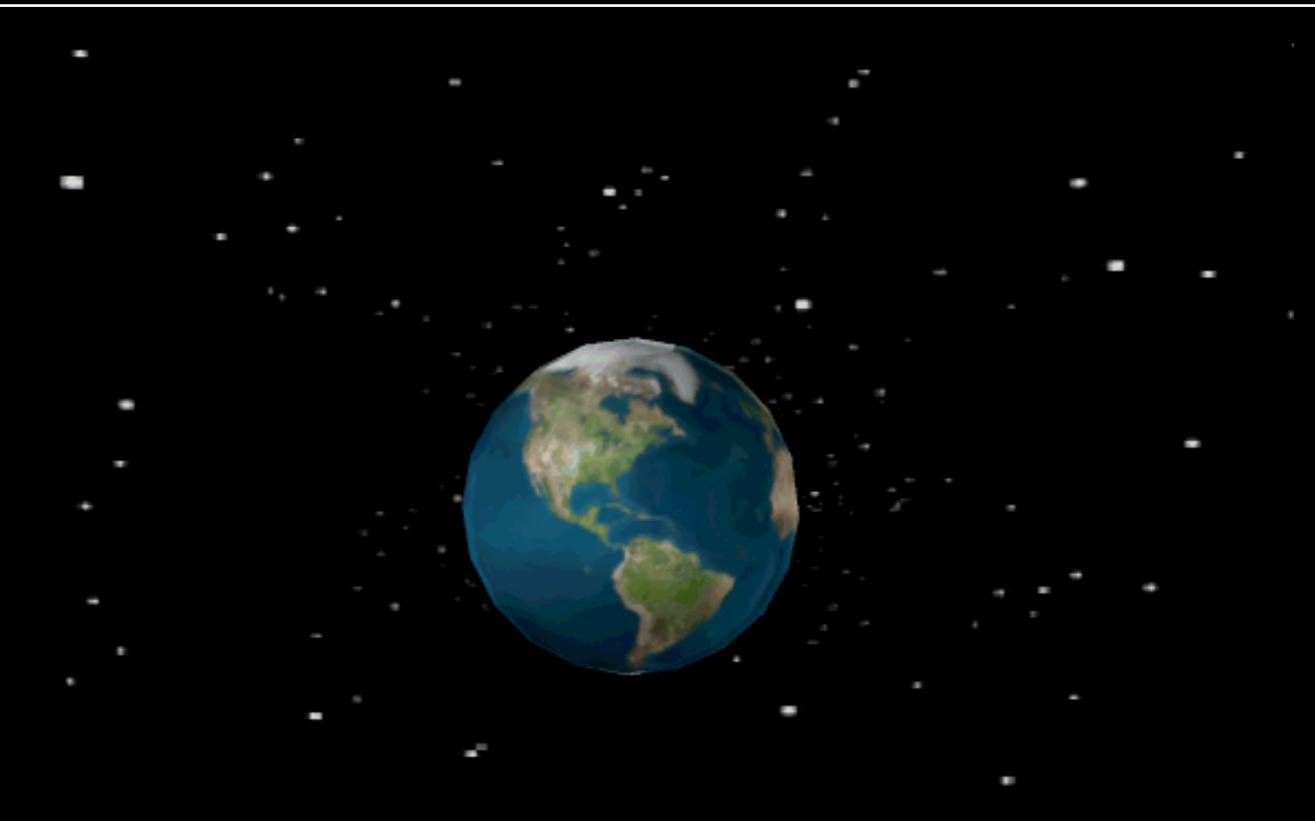
 $5m = mv_8 \cos 30 + mv_c \cos \theta_c$

 $v_c = \frac{5.0}{(\sin 60 \cot 30 + \cos 60)} = 2.5 \text{m/s}$

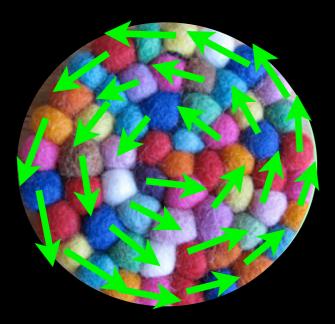
and:

$$v_8 = (2.5 \text{m/s}) \frac{\sin 60}{\sin 30} = 4.33 \text{m/s}$$





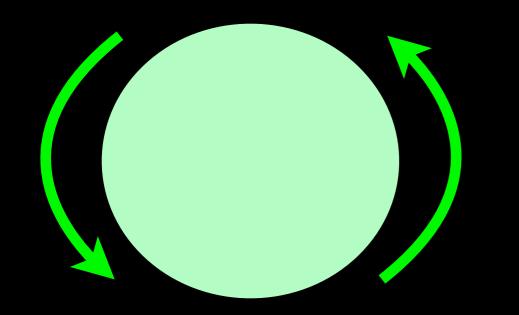
How do we calculate the motion of a rotating disc?



We could use circular motion to give each point a speed and direction

.... but that would be slow!

How do we calculate the motion of a rotating disc?



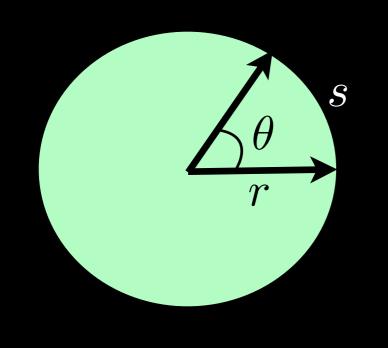
rigid body: all points remain fixed relative to one another

We could use circular motion to give each point a speed and direction

.... but that would be slow!

Easier to say that the disc rotates with 800 revolutions per minute (rpm)

Angular velocity



Rate of rotation: change in angle with time

 $\bar{\omega} = \frac{\Delta\theta}{\Delta t} \text{ rad/s} \quad \text{aver}$ $\omega = \lim_{\Delta t \to 0} \frac{\Delta\theta}{\Delta t} = \frac{d\theta}{dt}$

instantaneous angular velocity

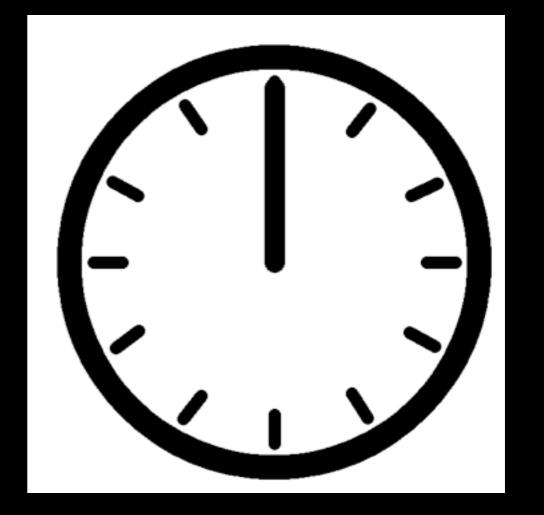
average angular velocity

For small
$$\theta$$
: $\theta = \frac{s}{r}$ [rad]
 $\frac{d\theta}{dt} = \frac{1}{r}\frac{ds}{dt} \rightarrow v = rw$
 $\omega \qquad v$

Quiz

What is the angular speed of the hour hand of a clock?

- (a) 1.45×10^{-4} rads⁻¹
 - (b) 1.75×10^{-3} rads⁻¹
 - (c) 0.0083 rads^{-1}
 - (d) 0.1 rads^{-1}



Quiz

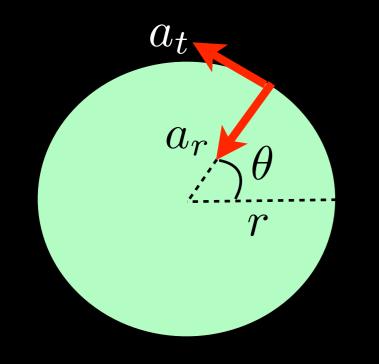
What is the angular speed of the hour hand of a clock?

 $\omega_{\rm hr} = \frac{1 \, \rm rev}{12 \, \rm hr}$ $= \frac{2\pi}{12 \times 3600}$

 $= 1.45 \times 10^{-4} \,\mathrm{rads}^{-1}$



Angular acceleration



$$\alpha = \lim_{\Delta t \to 0} \frac{\Delta \omega}{\Delta t} = \frac{d\omega}{dt} \quad \text{rad/s}^2$$

Tangential acceleration speeds up or slows down rotation:

$$a_t = \frac{dv}{dt} = r\frac{d\omega}{dt} = r\alpha$$

There is still radial acceleration:

$$a_r = \frac{v^2}{r} \quad \overrightarrow{v \equiv r\omega} \quad a_r = \omega^2 r$$

Linear and angular quantities:

Linear Quantity	Angular Quantity
Position x	Angular Position θ
Velocity $v = \frac{dx}{dt}$	Angular velocity $w = \frac{d\theta}{dt}$
Acceleration $a = \frac{dv}{dt} = \frac{d^2x}{dt^2}$	Angular acceleration $\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$

Eq. for constant linear accelerationEq. for angular acceleration $v = v_0 + at$ $\omega = \omega_0 + \alpha t$ $x = x_0 + v_0 t + \frac{1}{2}at^2$ $\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$ $v^2 = v_0^2 + 2a(x - x_0)$ $\omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0)$

Quiz

- A merry-go-round starts from rest and accelerates with angular acceleration of 0.010 rad/s^2 for 14 s.
 - (a) How many revolutions does it make during this time?
 - (b) What is the average angular speed?

- (1) 0.16 rev, 0.01 rad/s
- (2) 0.98 rev, 0.07 rad/s
- (3) 0.16 rev, 0.07 rad/s
- (4) 0.98 rev, 0.01 rad/s



A merry-go-round starts from rest and accelerates with angular acceleration of 0.010 rad/s^2 for 14 s.

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$$



$$\Delta \theta = \theta - \theta_0 = \frac{1}{2} (0.010 \,\mathrm{rads}^{-1}) (14 \,\mathrm{s})^2$$
$$= 0.98 \,\mathrm{rad} = 0.98 \,\mathrm{rad} \left(\frac{1 \,\mathrm{rev}}{2\pi \,\mathrm{rad}}\right) = 0.16 \,\mathrm{rev}$$

$$\omega = \frac{\Delta \theta}{\Delta t} = \frac{0.98 \,\mathrm{rad}}{14 \,\mathrm{s}} = 0.07 \,\mathrm{rad/s}$$

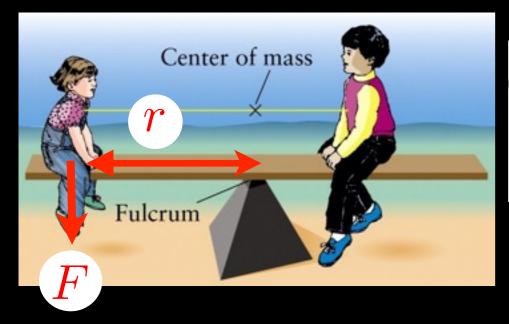
Quiz

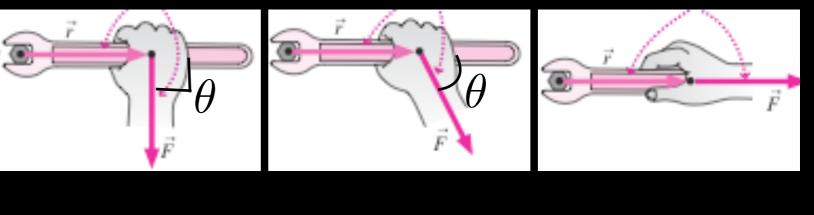
We have angular equivalents of x, v and a

What about for $\bar{F} = m\bar{a}$?

Need angular equivalents for force and mass.

Forces that change rotational motion depend on.....





direction of applied force

Vm]

magnitude of the force and distance from the axis

Angular force, Torque:

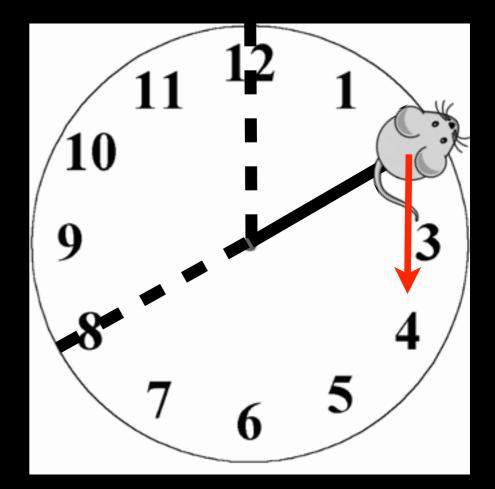
$$au = rF\sin heta$$
 [

Quiz

A 55-g mouse runs out to the end of the 17-cm long minute hand of a clock when the clock is at 10 past the hour.

What torque does the mouse's weight exert about the rotation axis of the clock hand?

- (I) 0.1Nm
- **(2)** 0.016Nm
- **(3)** 0.09Nm
- (4) $7.9 \times 10^{-2} \text{Nm}$



A 55-g mouse runs out to the end of the 17-cm long minute hand of a clock when the clock is at 10 past the hour.

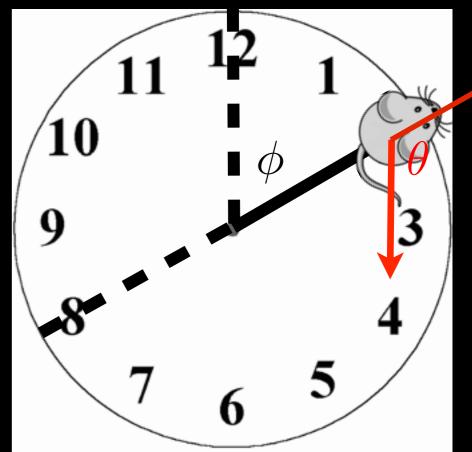
What torque does the mouse's weight exert about the rotation axis of the clock hand?

From clock face:
$$\phi = \frac{180^{\circ}}{3} = 60^{\circ}$$

$$\theta = 180^{\circ} - 60^{\circ} = 120^{\circ}$$

 $\tau = rF\sin\theta$

 $= (0.17 \text{ m})(0.055 \text{ kg})(9.81 \text{ m/s}^2) \sin(120^\circ)$ $= 7.9 \times 10^{-2} \text{ Nm}$

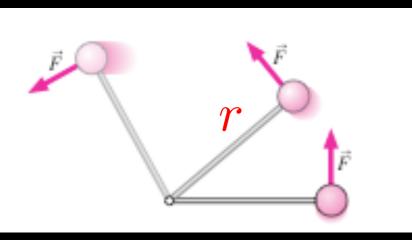




What about mass?

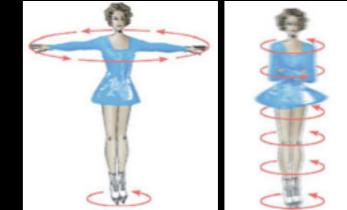
It is easier to move an object if its mass is low

It is easier to rotate an object if its mass is centred near the rotation axis



$$F = ma_t = m\alpha r$$
$$\tau = rF\sin 90 = rF$$
$$\tau = (mr^2)$$





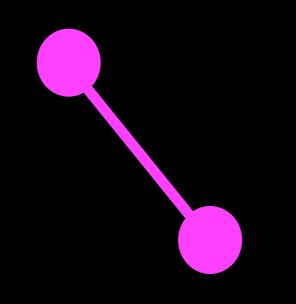


frotational inertia, I

Newton's 2nd law for rotation:

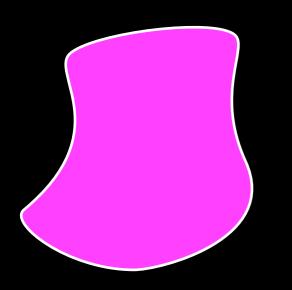
$$\tau = I\alpha$$

Calculating rotational inertia



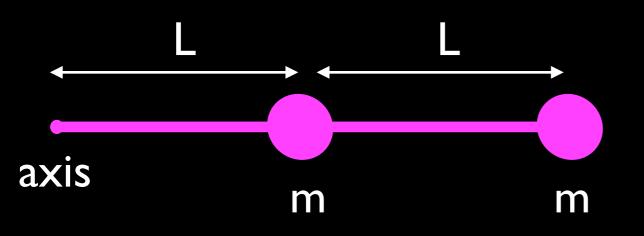
Discrete mass points:

$$I = \Sigma m_i r_i^2$$



Continuous matter:

$$I = \int r^2 dm$$

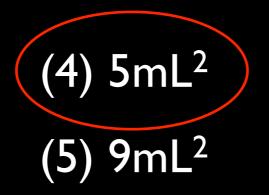


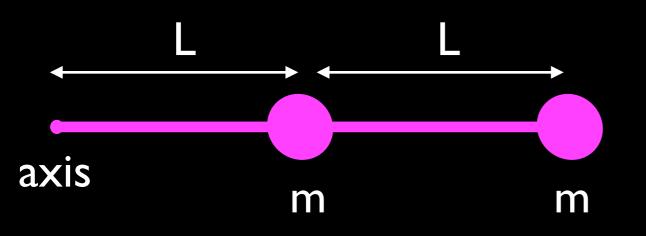
A light (no mass) rod of length = 2L. 2 heavy masses (each mass = m) attached at the end and middle. What is the rotational inertia about the axis?

(1) mL^{2}

(2) $2mL^2$

(3) 4mL²



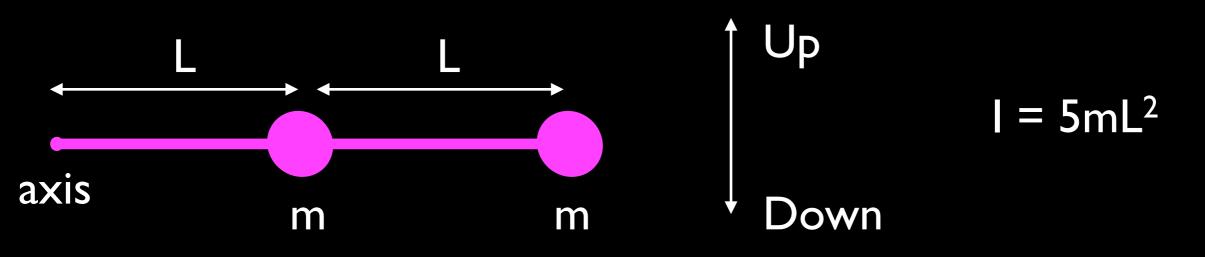


A light (no mass) rod of length = 2L. 2 heavy masses (each mass = m) attached at the end and middle. What is the rotational inertia about the axis?

Centre mass: $I = mL^2$

End mass: $I = m(2L)^2$

Total: $I = \Sigma m_i r_i^2 = 5 \text{mL}^2$

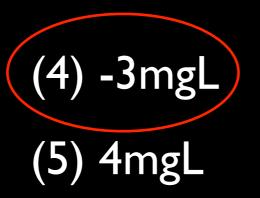


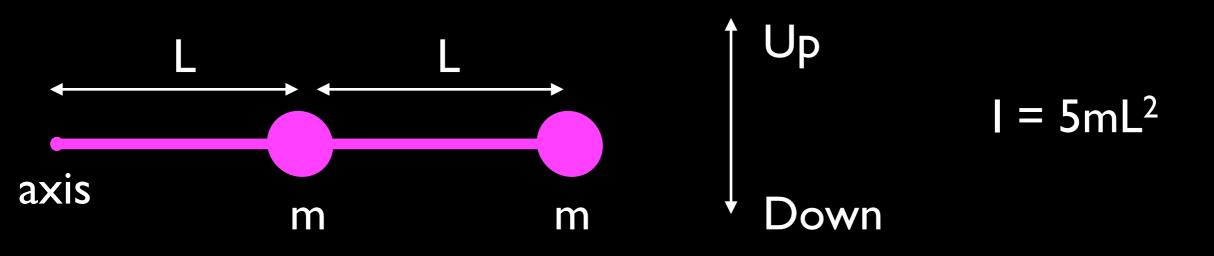
What is the net torque when it's released?

(I) 2mgL

(2) -2mgL

(3) 3mgL





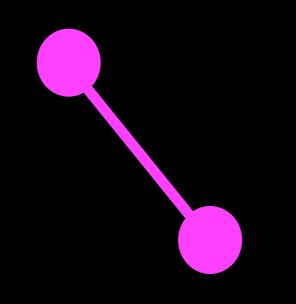
What is the net torque when it's released?

 $\tau = rF\sin 90$

 $= L(-mg)\sin(0) + (2L)(-mg)\sin(0)$

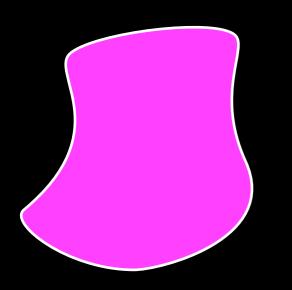
= -3mgL

Calculating rotational inertia



Discrete mass points:

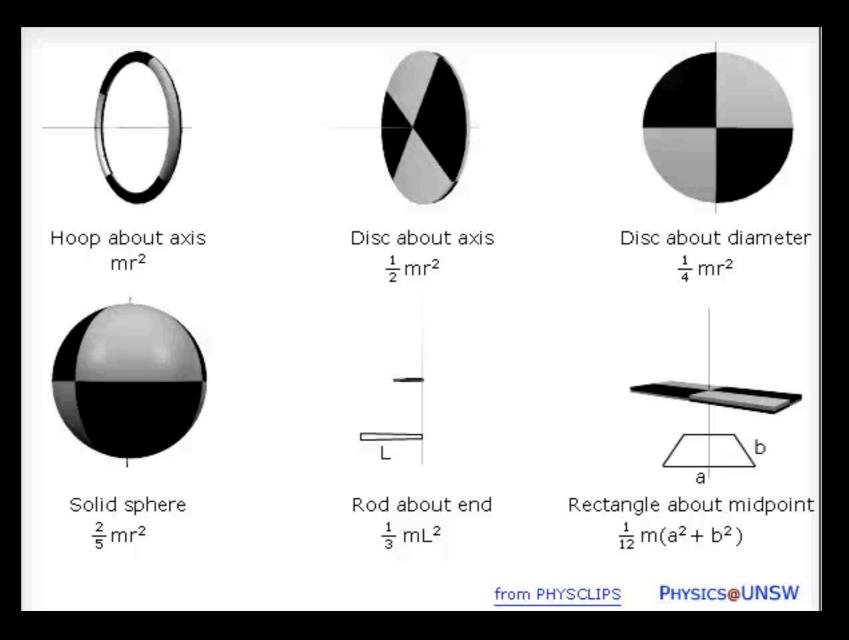
$$I = \Sigma m_i r_i^2$$



Continuous matter:

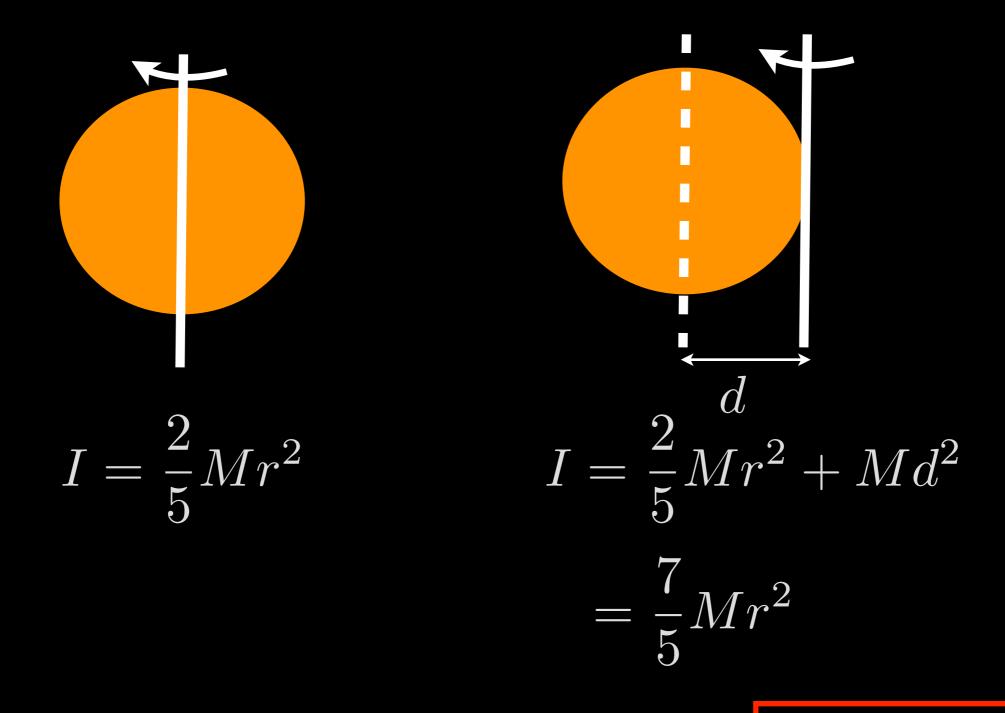
$$I = \int r^2 dm$$

Rotational inertia



Also p 163 in textbook

If we know I through the centre of mass of the object:



we can calculate I through any parallel axis.

$$I = I_{\rm cm} + Md^2$$